

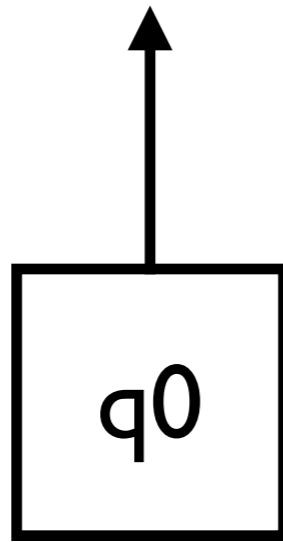
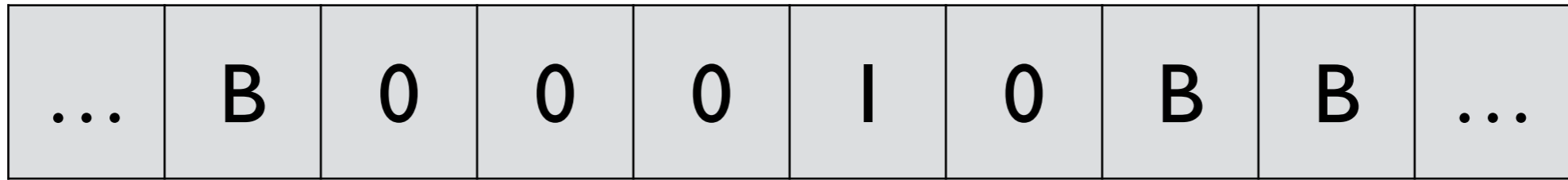
Example 4. Design a Turing machine that computes $f(m, n)$.

$$f(m, n) = \max(m - n, 0) = \text{if } m \geq n \text{ then } m - n \text{ else } 0$$

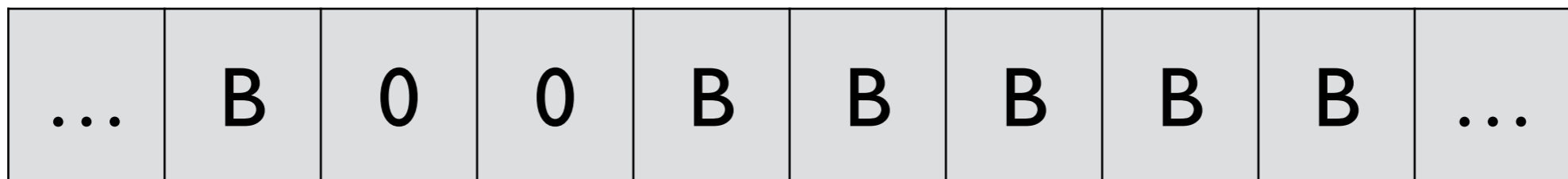
$$M = (\{q_0, q_1, \dots, q_6\}, \{0, 1\}, \{0, 1, B\}, \delta, q_0, B, \{q_6\})$$

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

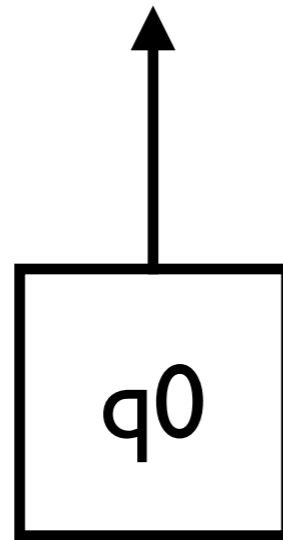
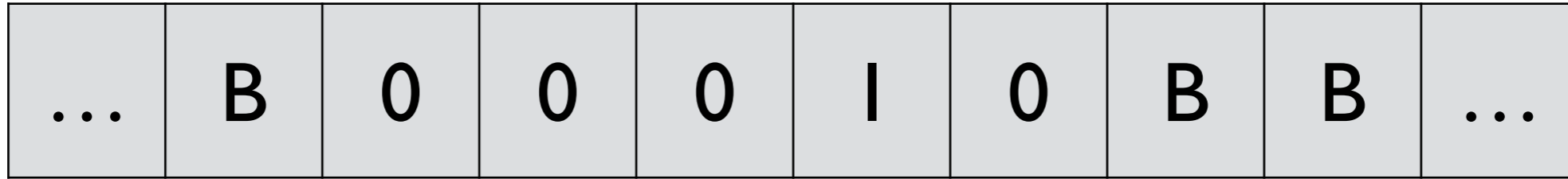
Initial machine configuration: e.g., $f(3, 1)$



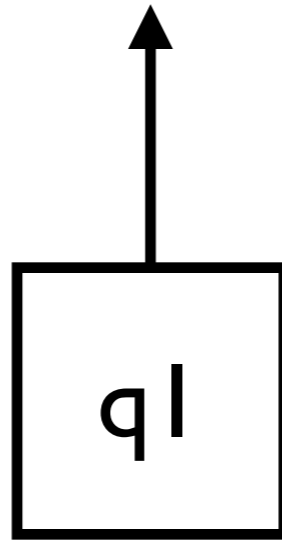
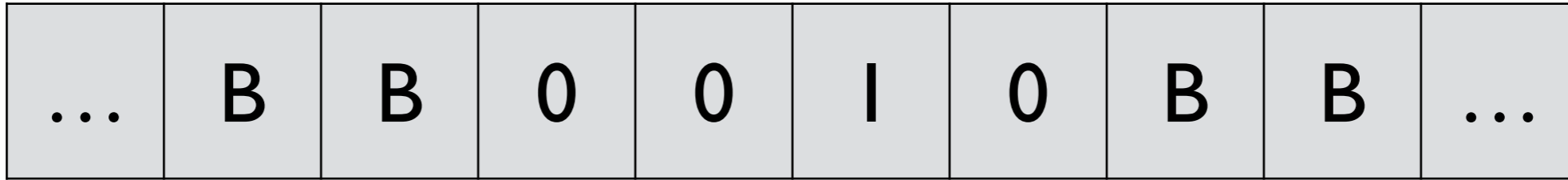
When the machine halts:



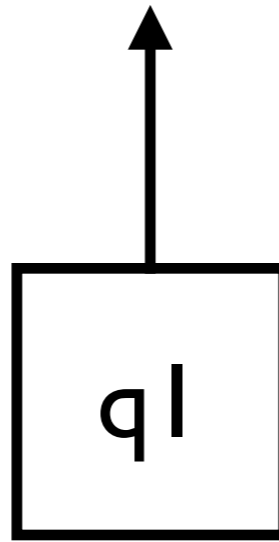
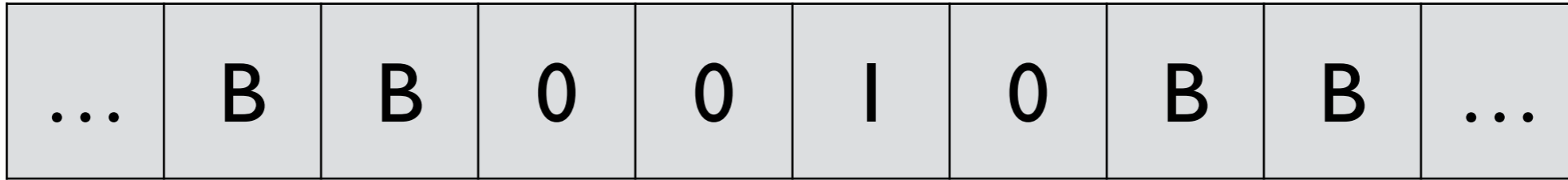
e.g., $f(3,2)$



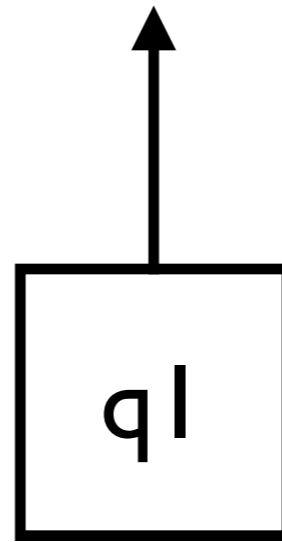
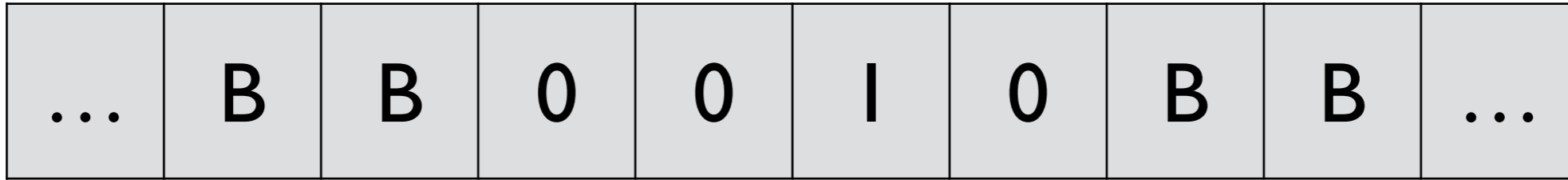
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



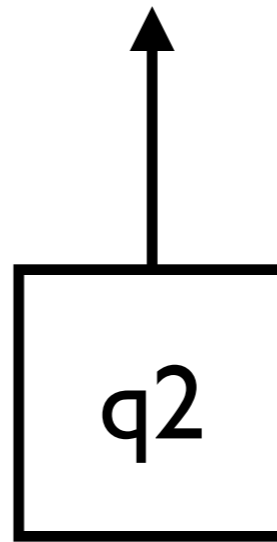
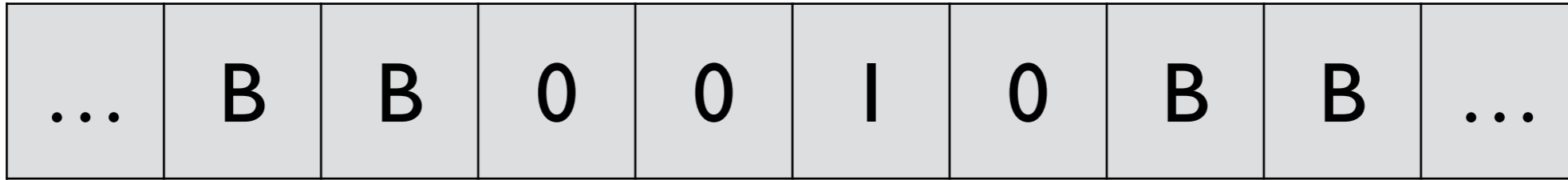
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



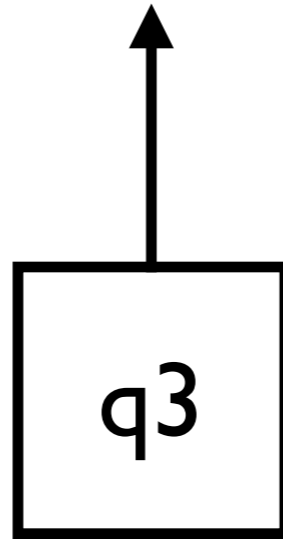
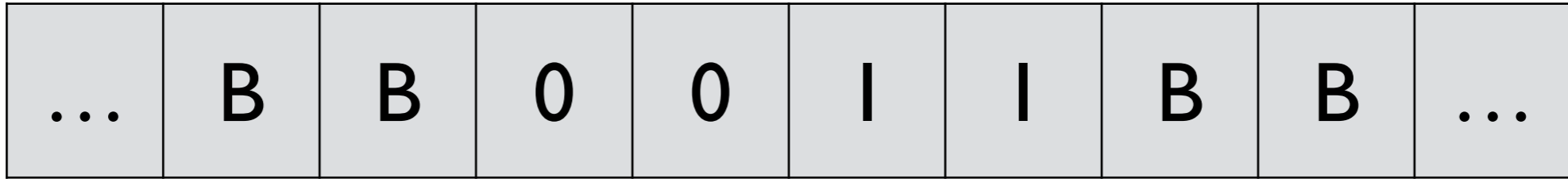
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



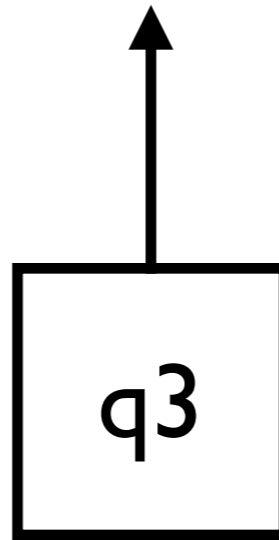
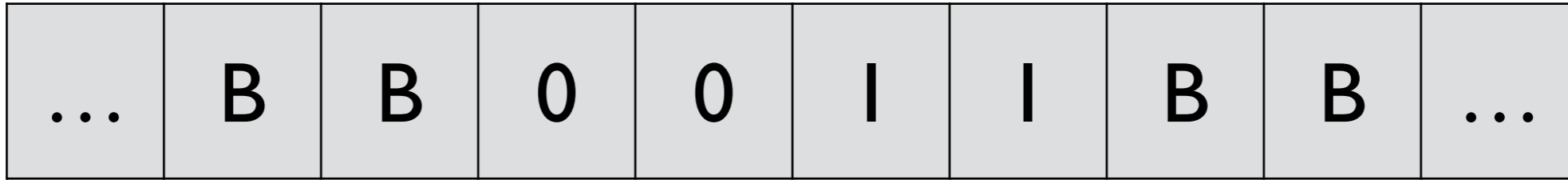
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



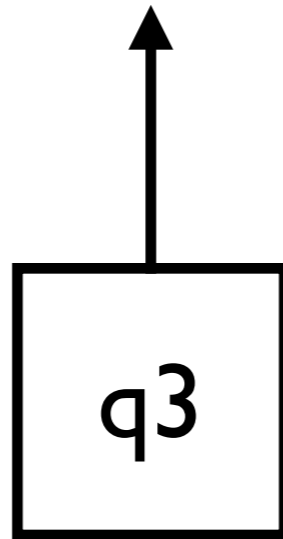
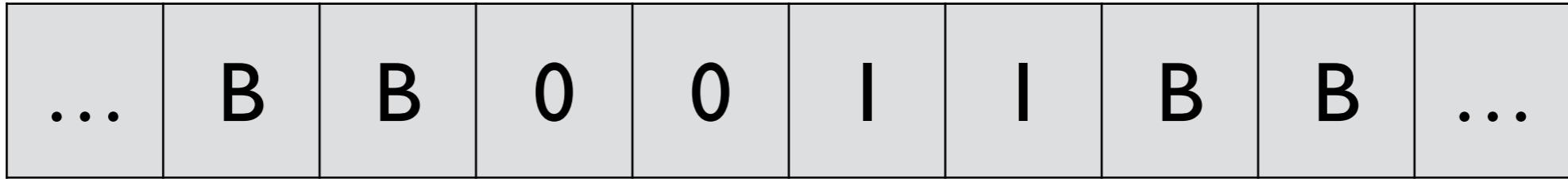
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



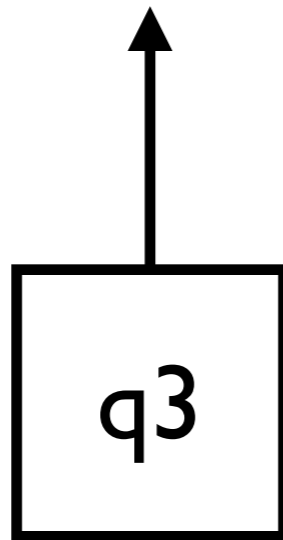
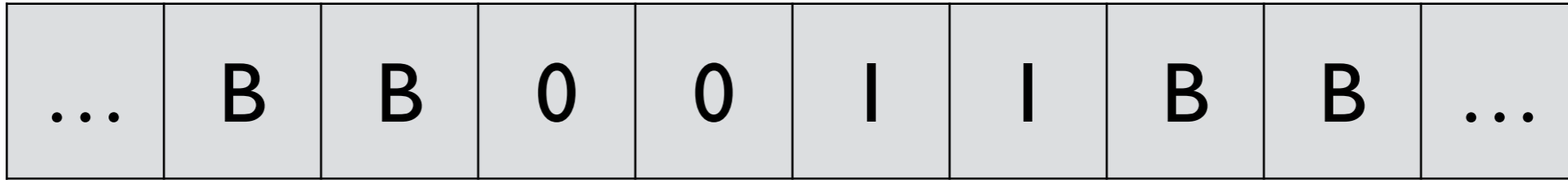
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



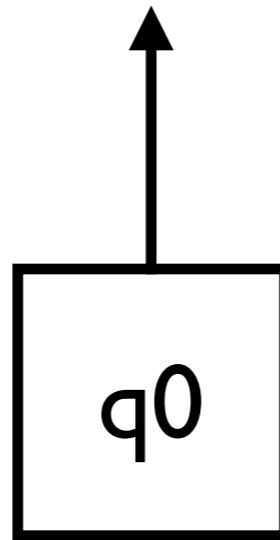
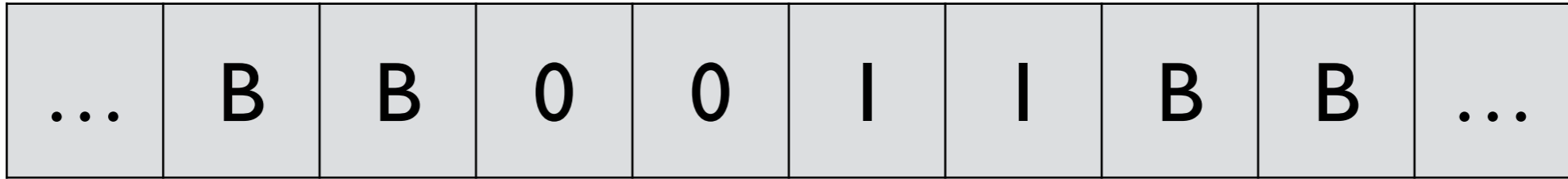
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



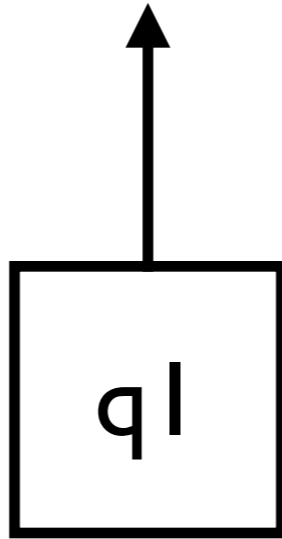
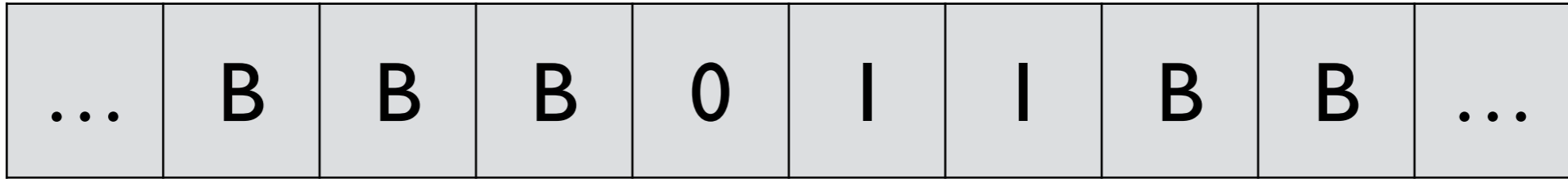
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



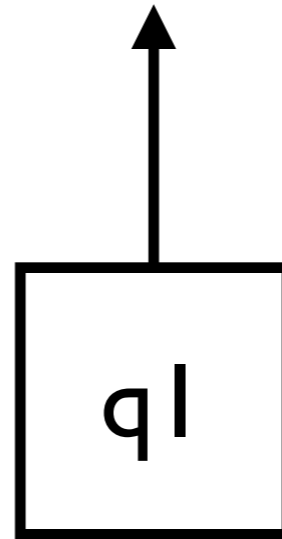
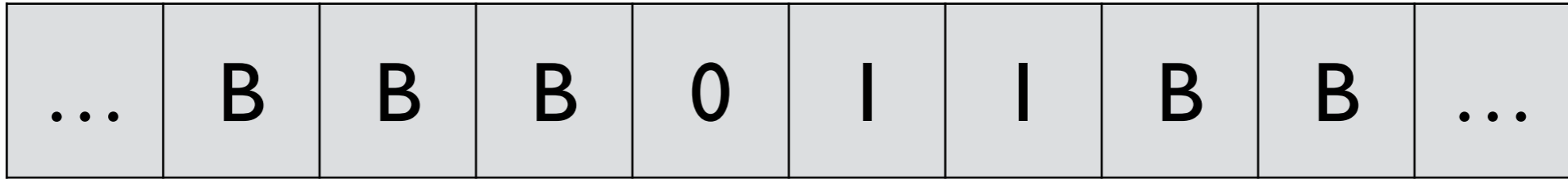
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



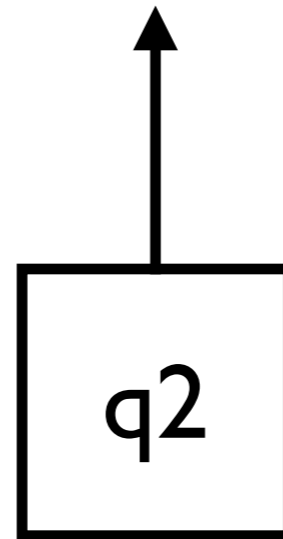
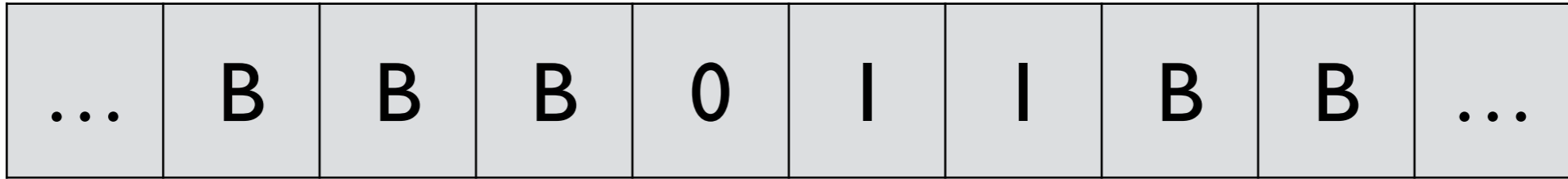
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



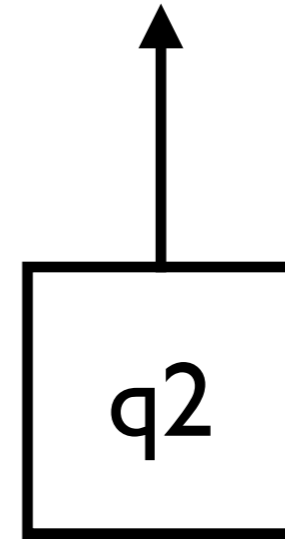
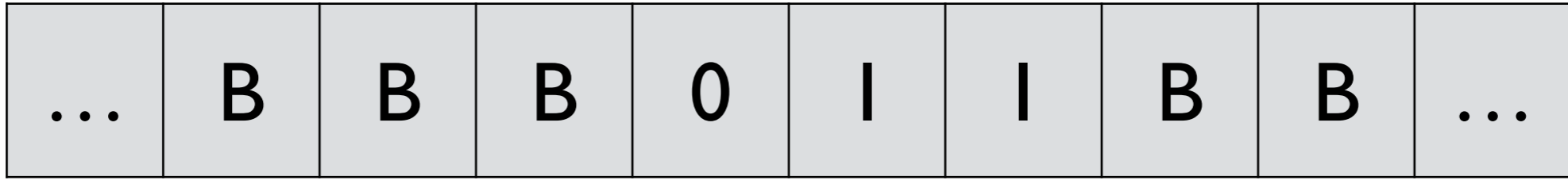
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



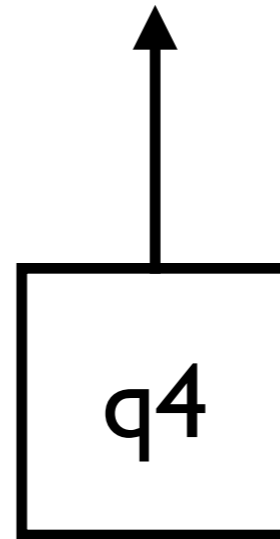
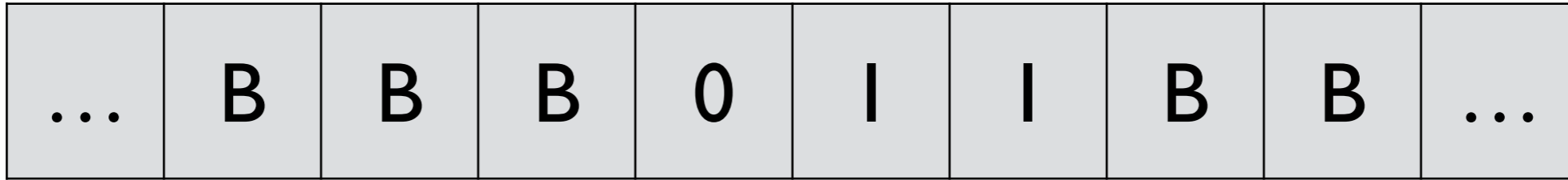
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



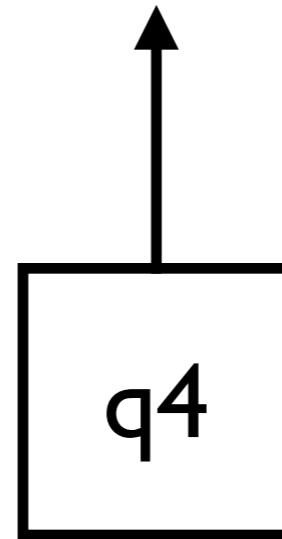
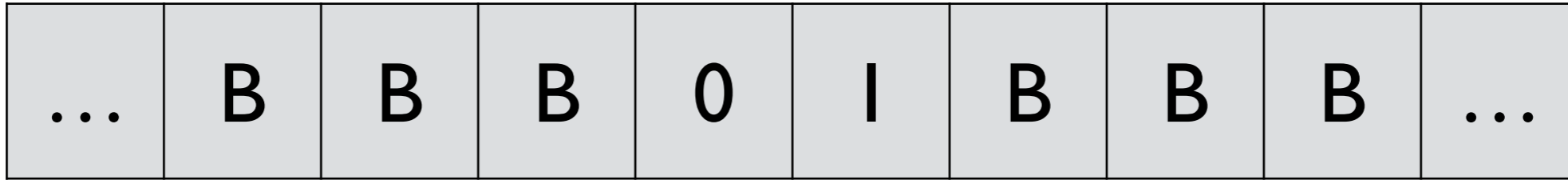
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



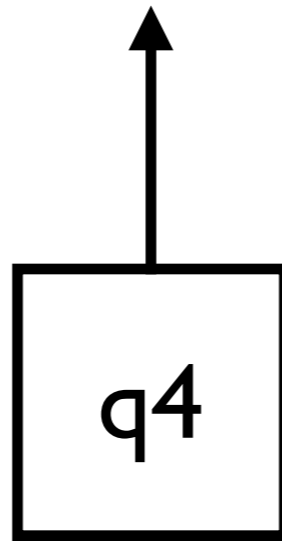
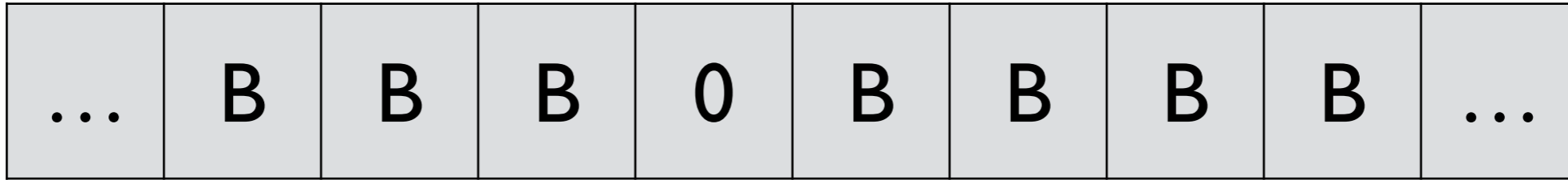
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



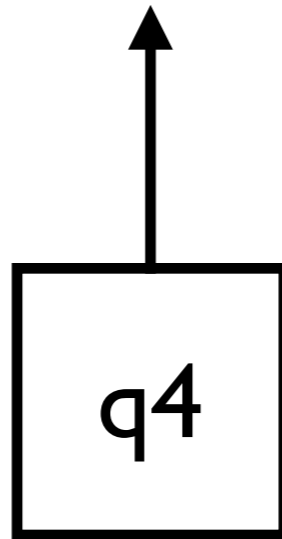
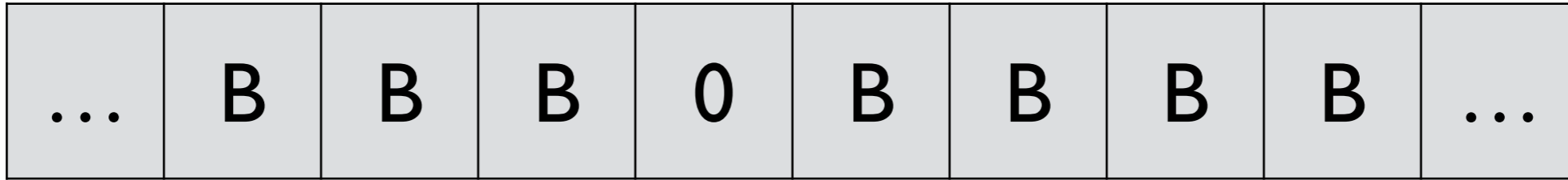
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



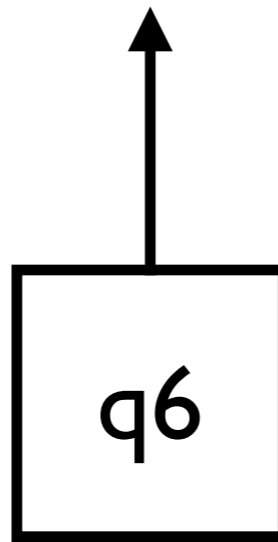
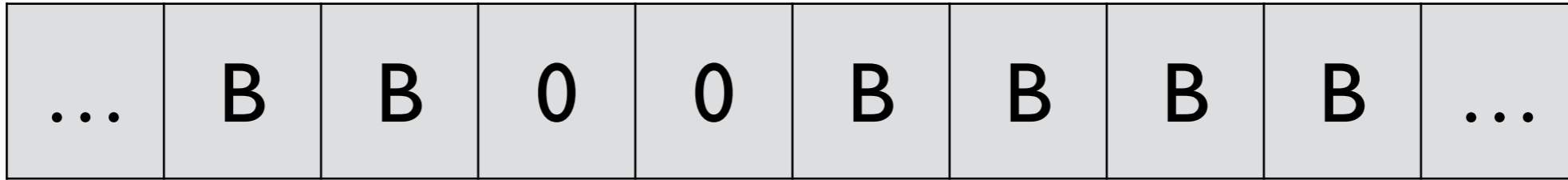
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

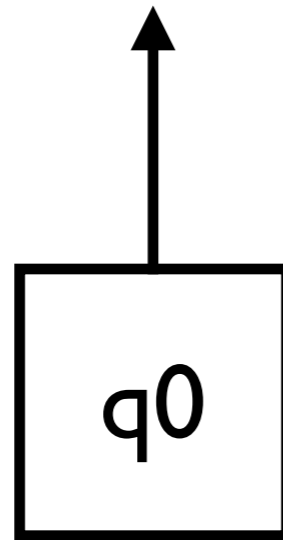
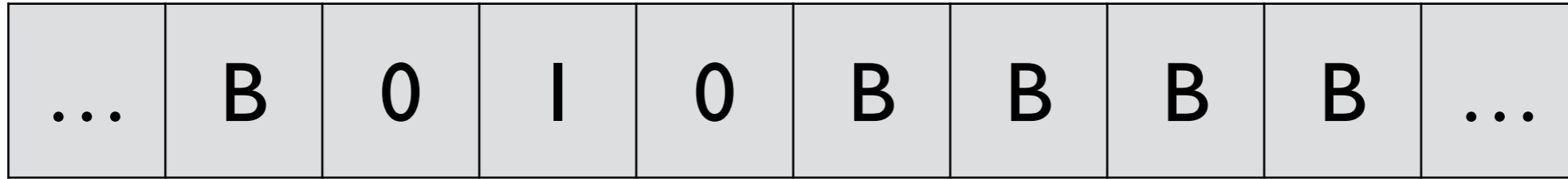


	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

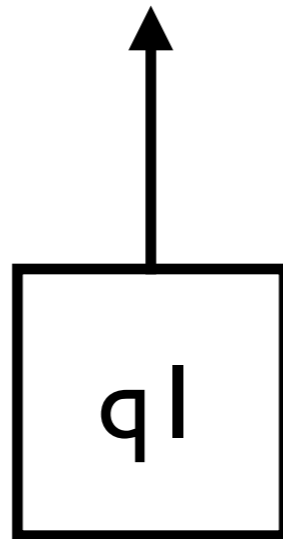
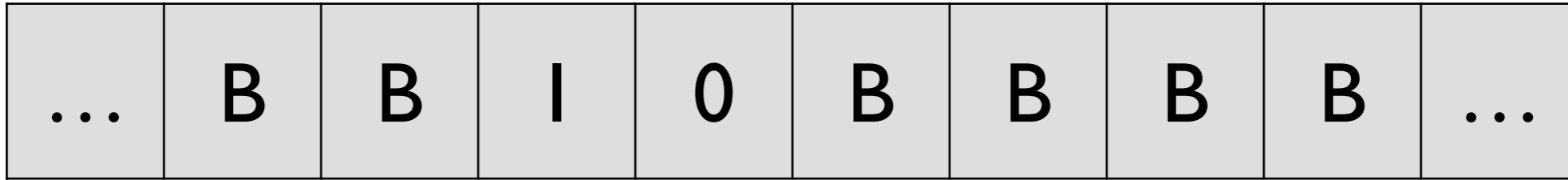


	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

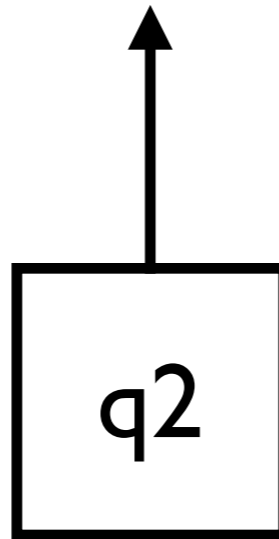
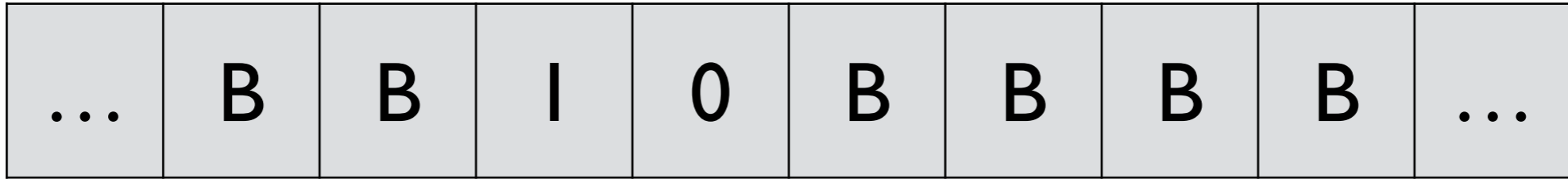
e.g., $f(l, l)$



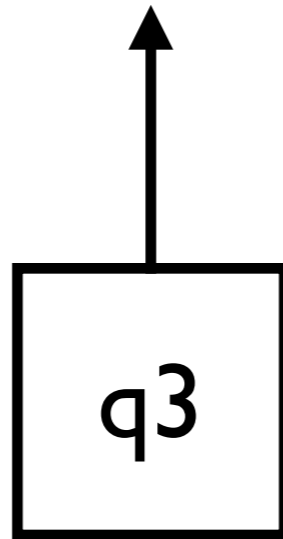
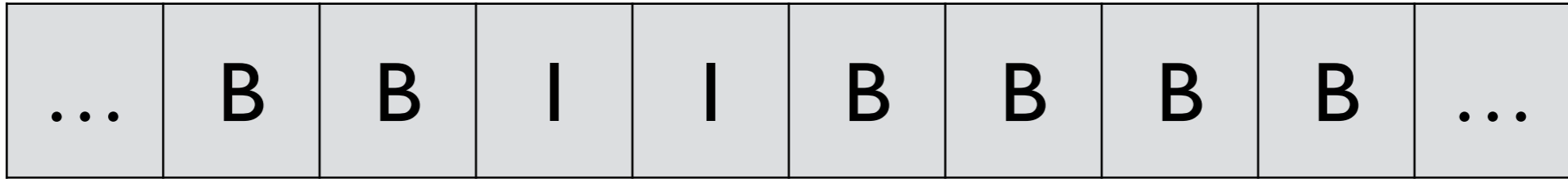
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



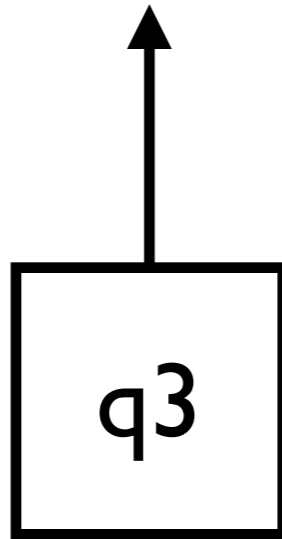
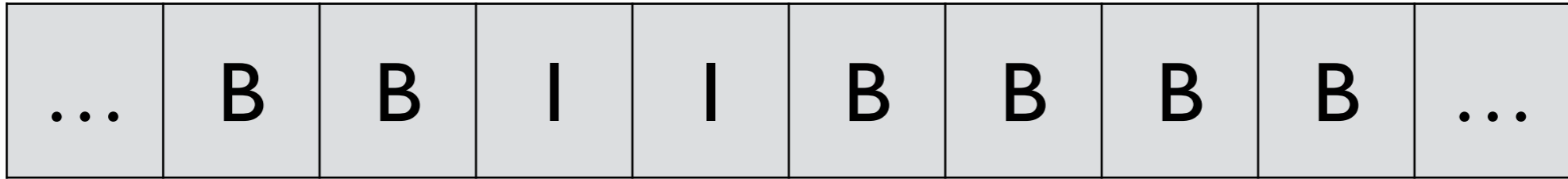
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



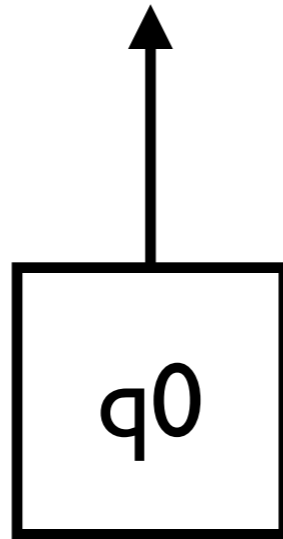
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



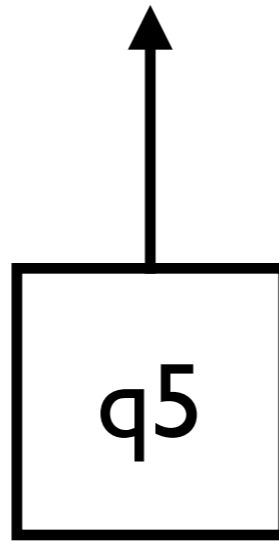
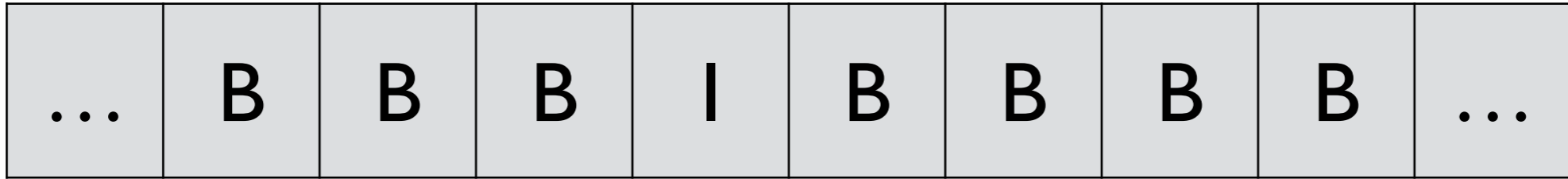
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



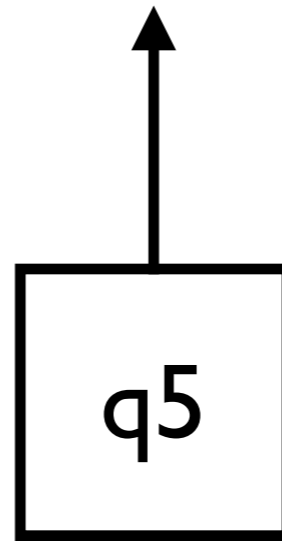
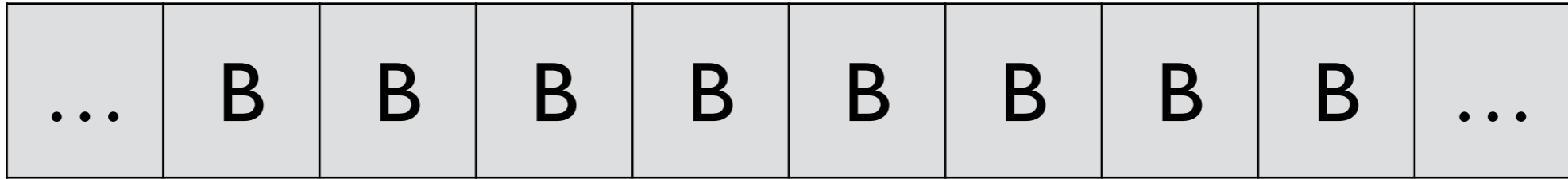
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



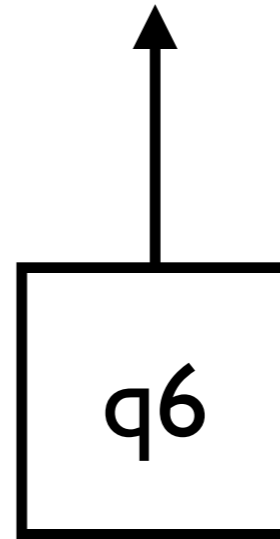
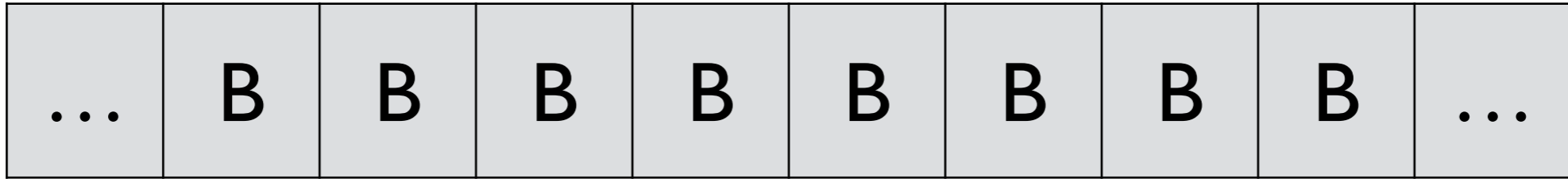
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

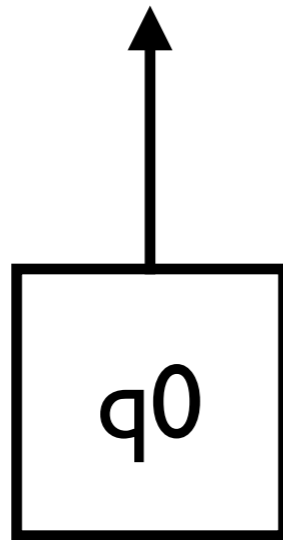
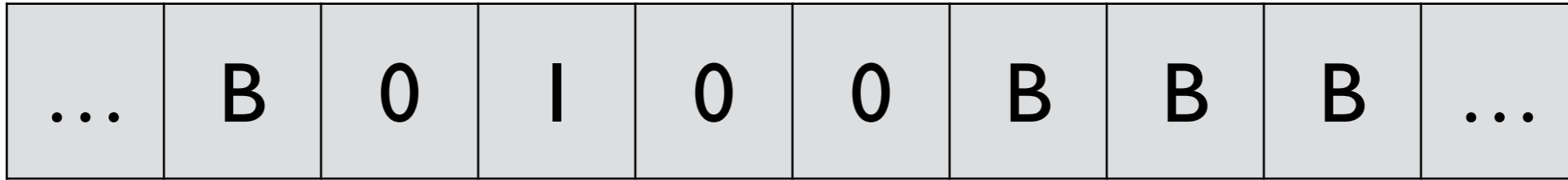


	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

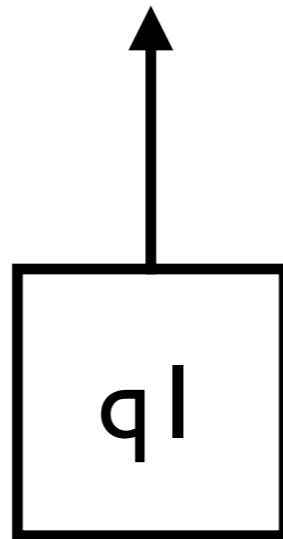
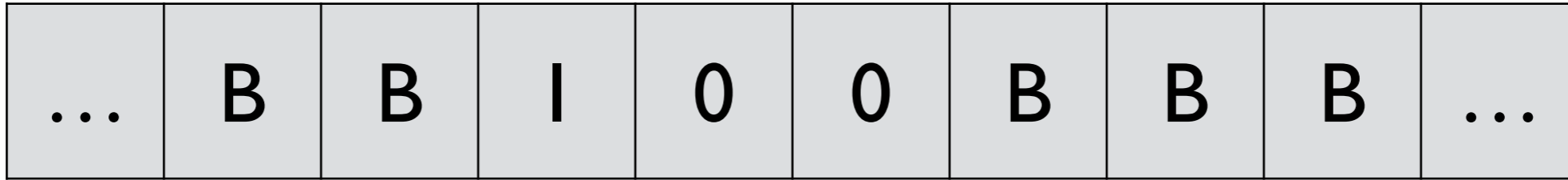


	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

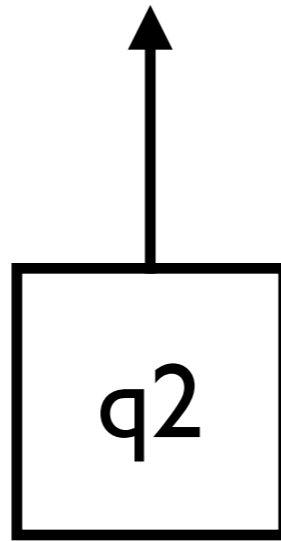
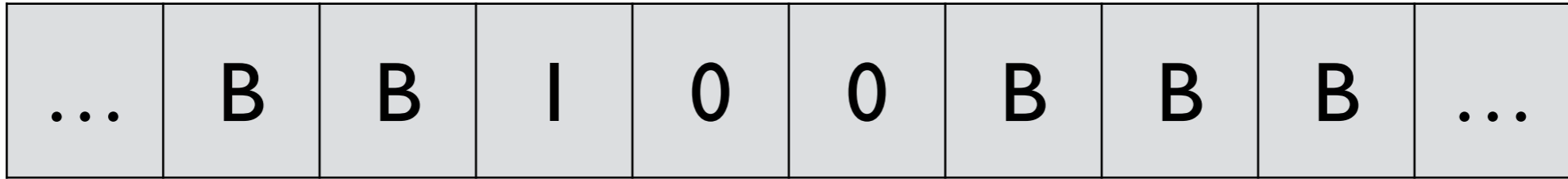
e.g., $f(1,2)$



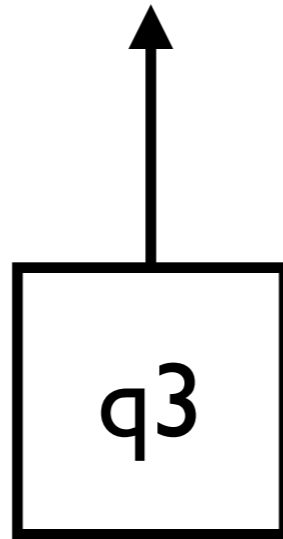
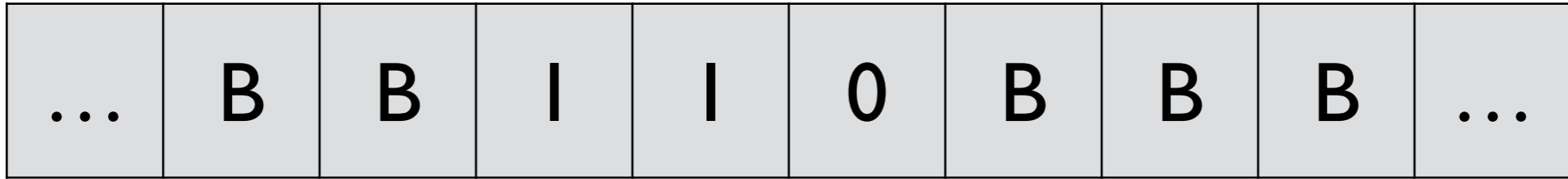
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



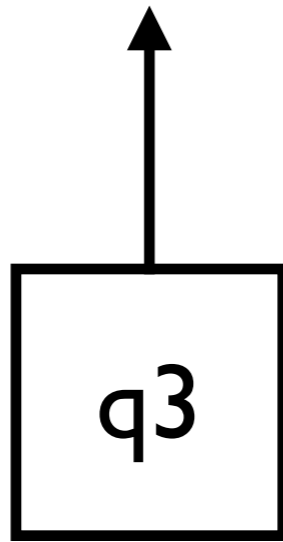
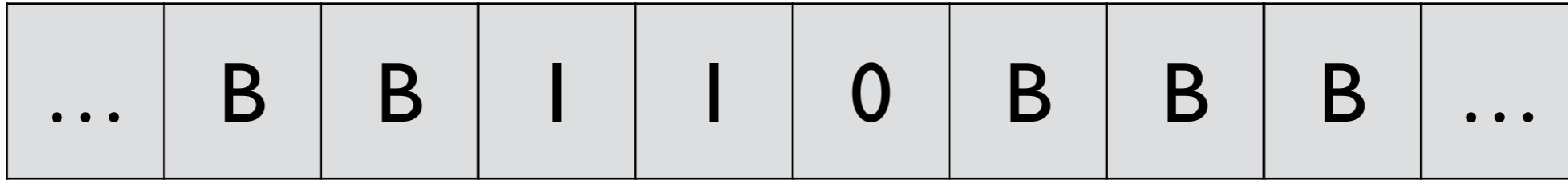
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



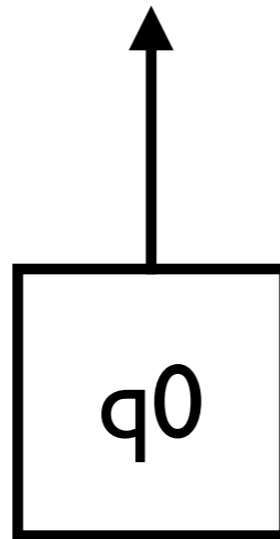
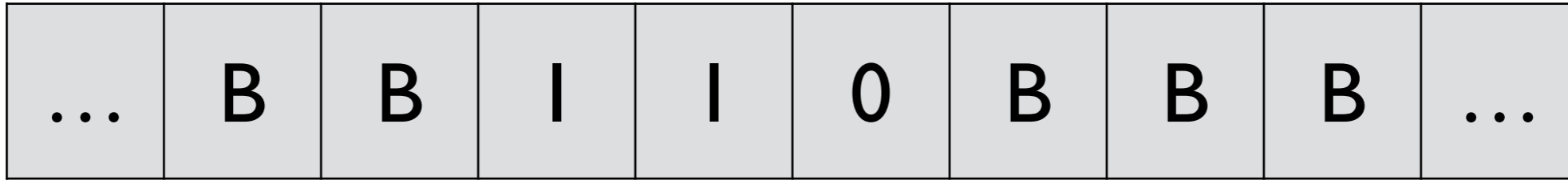
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



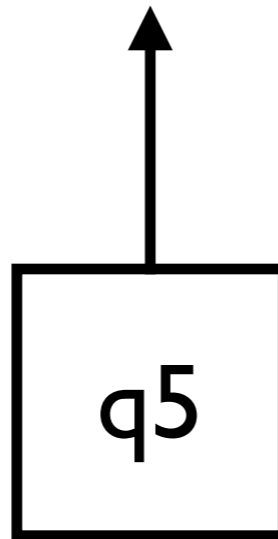
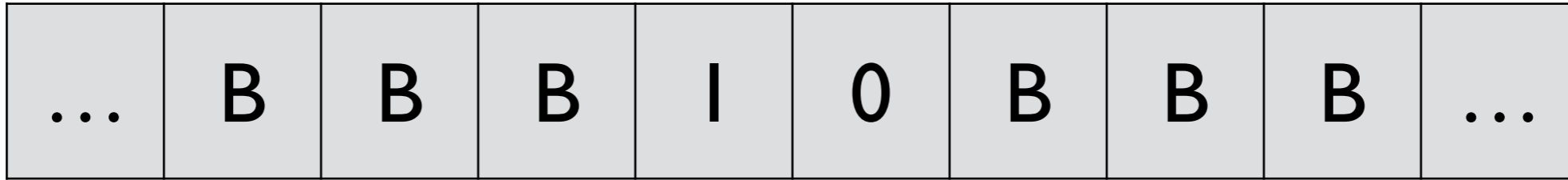
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



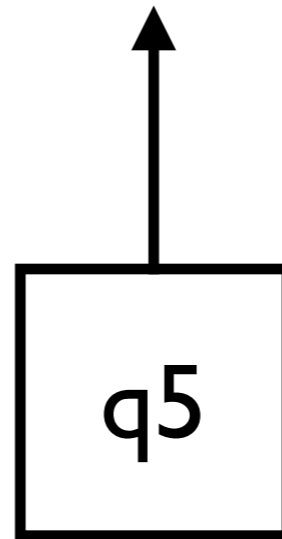
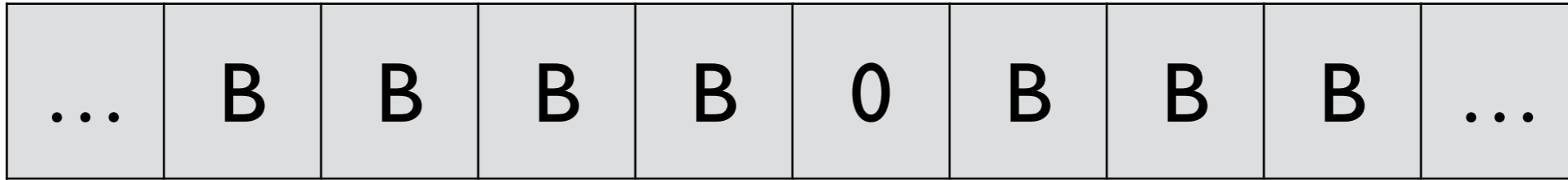
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



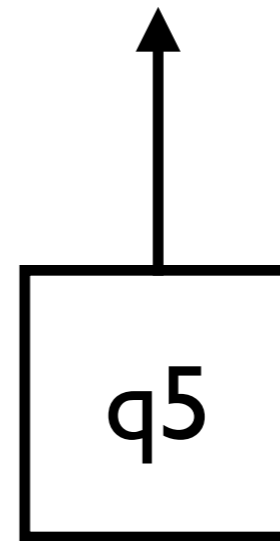
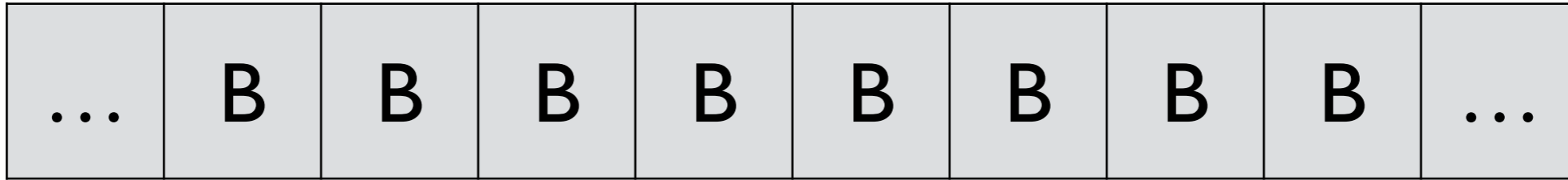
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



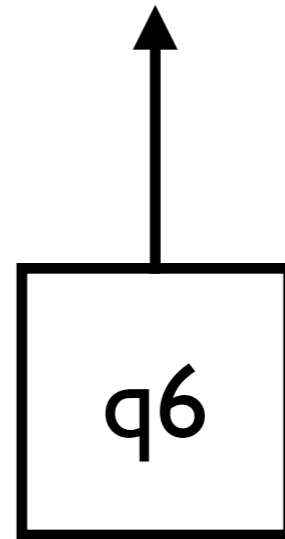
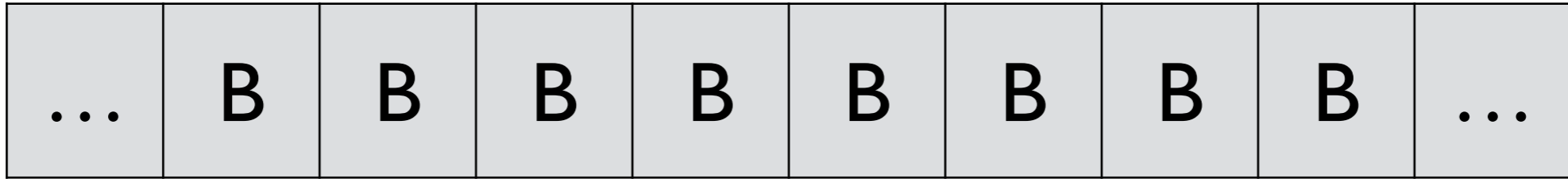
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



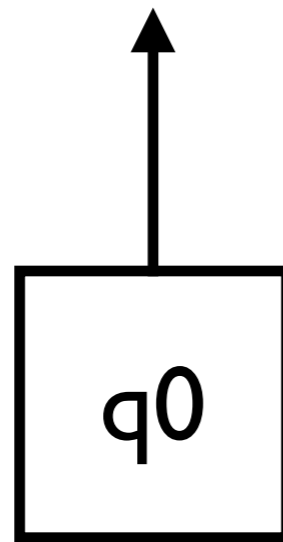
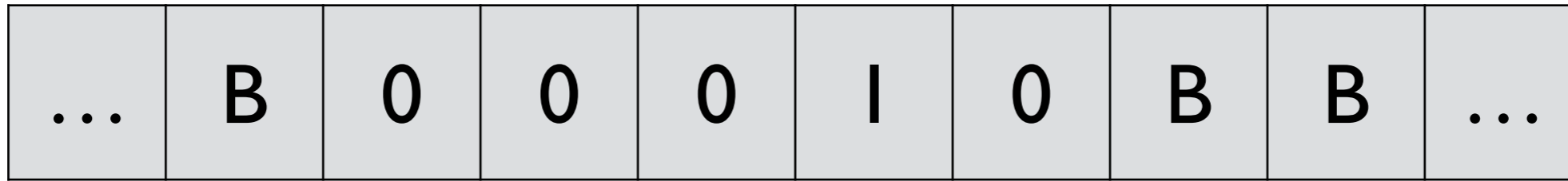
	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

Example, revisited

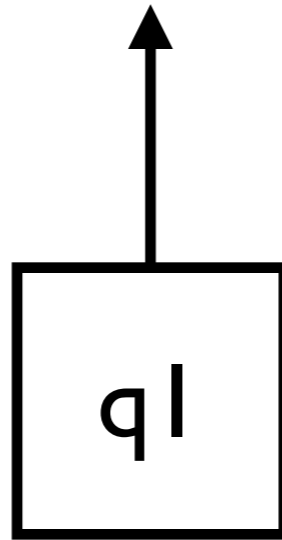
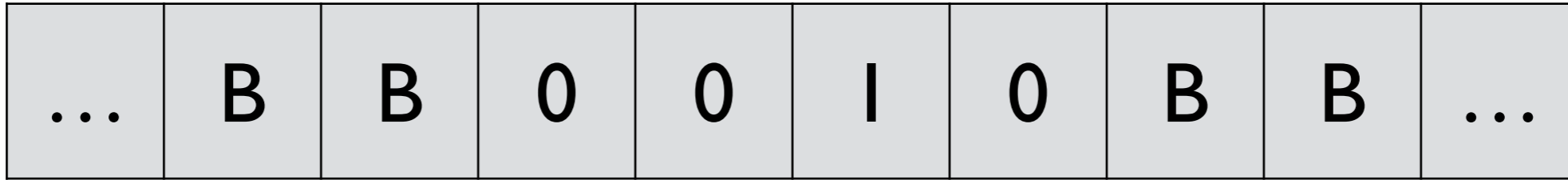
e.g., $f(3,2)$



Scanned 0 in q_0 , the cycle must repeat:

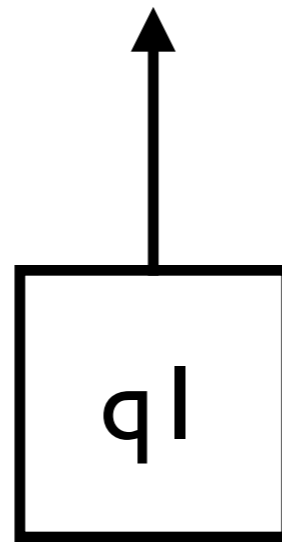
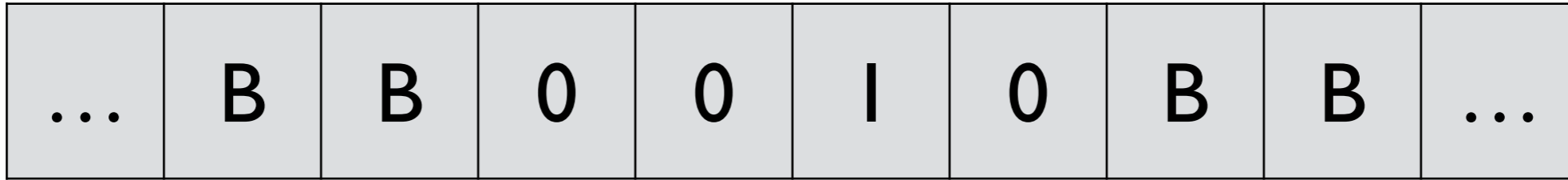
1. replace 0 by B
2. move right
3. enter q_1

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



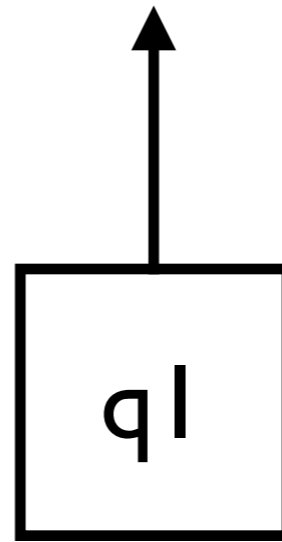
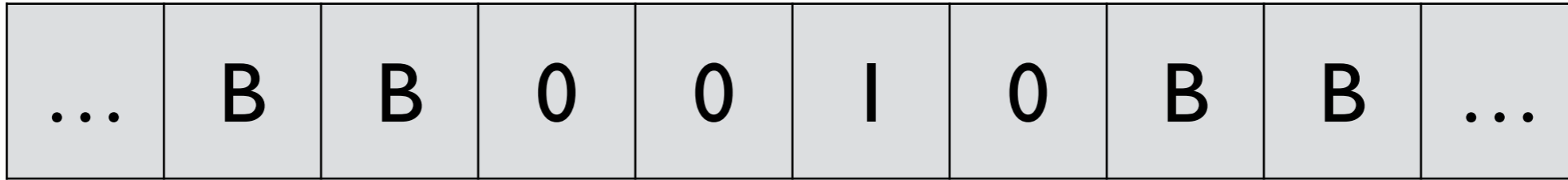
In q_1 , search right,
looking for leftmost 1

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



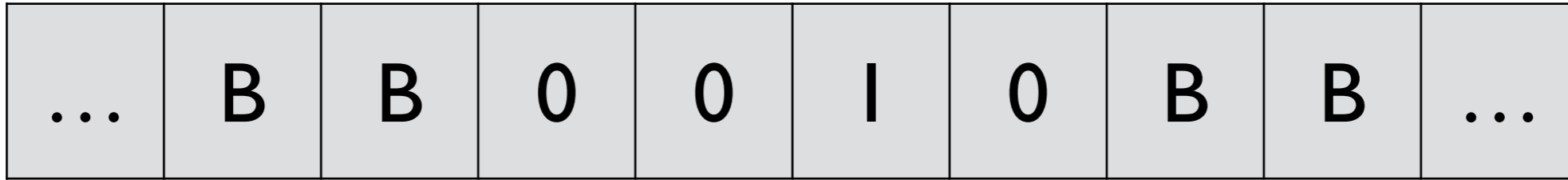
In q_1 , search right,
looking for leftmost 1

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

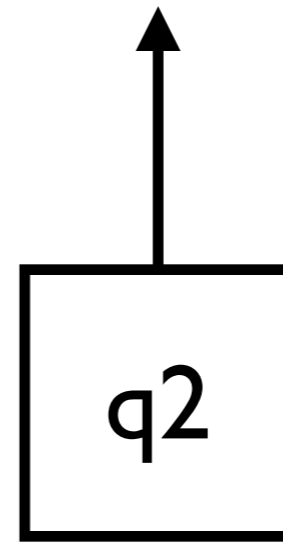


When found, enter q_2

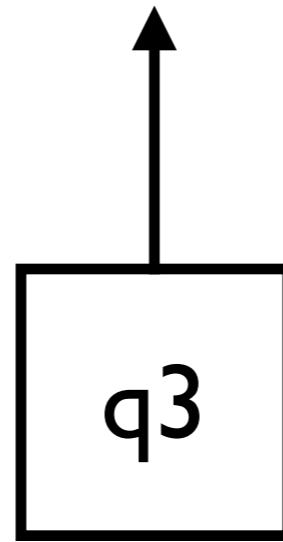
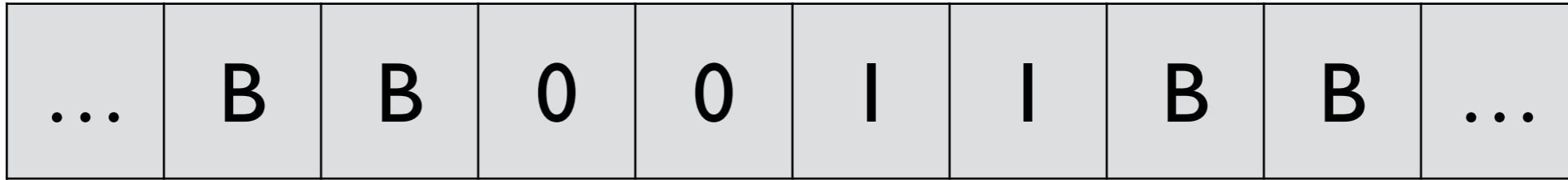
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



- In q_2 , move right until it finds 0
- When found, change it by 1
- enter q_3

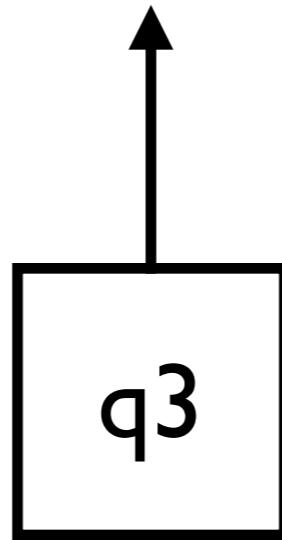
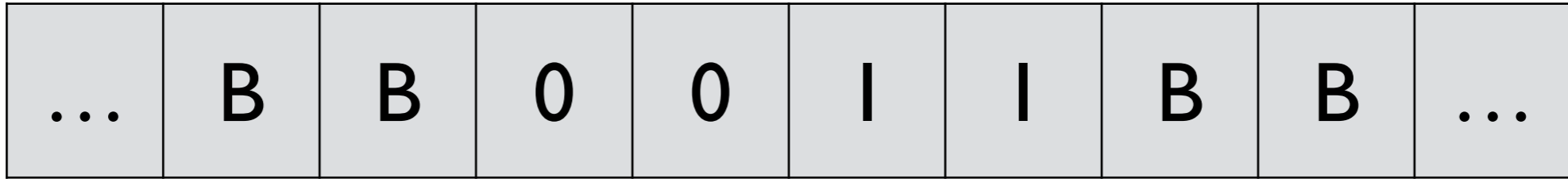


	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

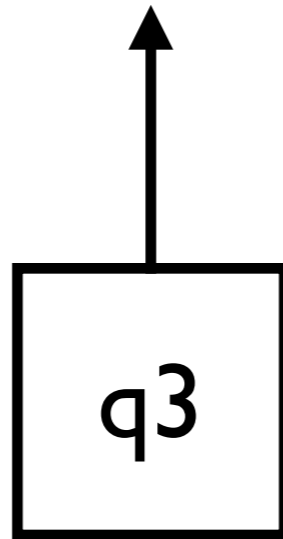
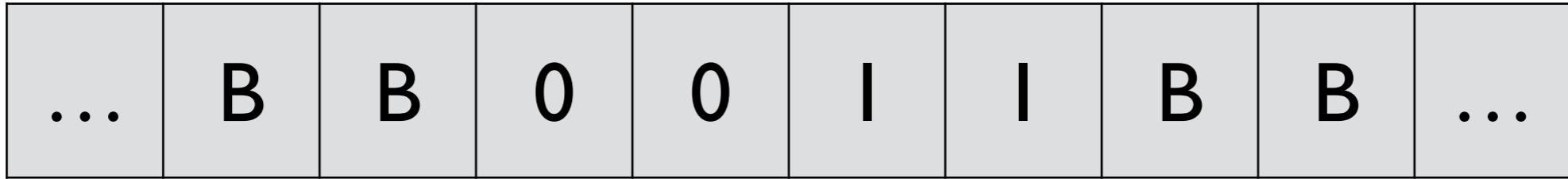


In q_3 , move left until it find B

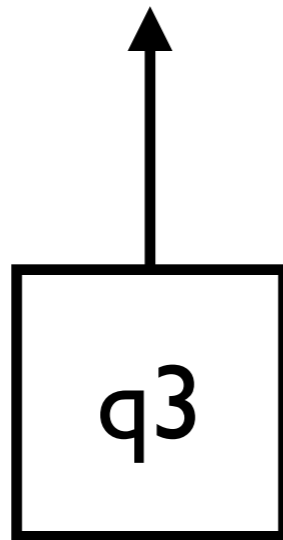
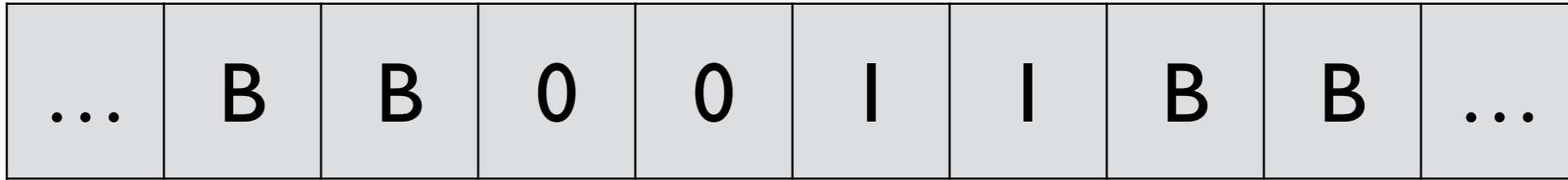
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

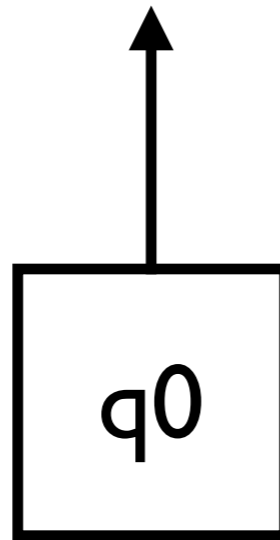
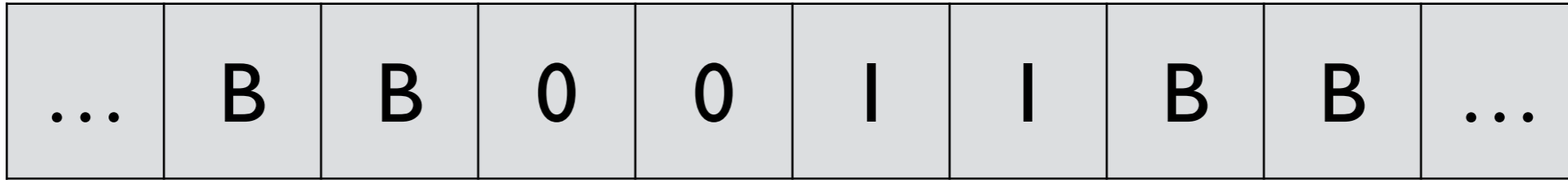


	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



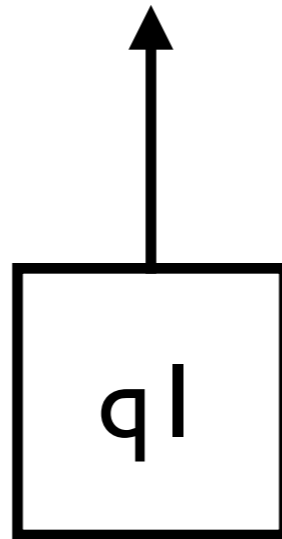
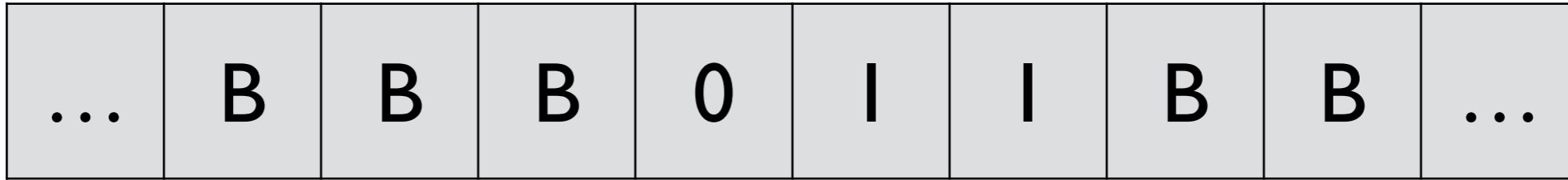
When B found, enter q_0 and begin the cycle

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



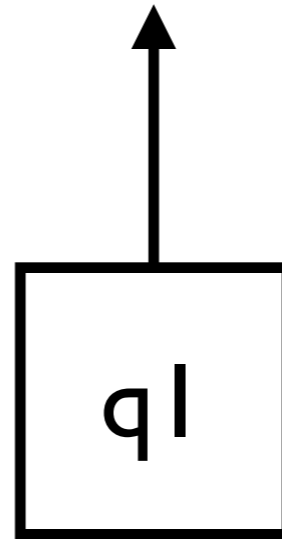
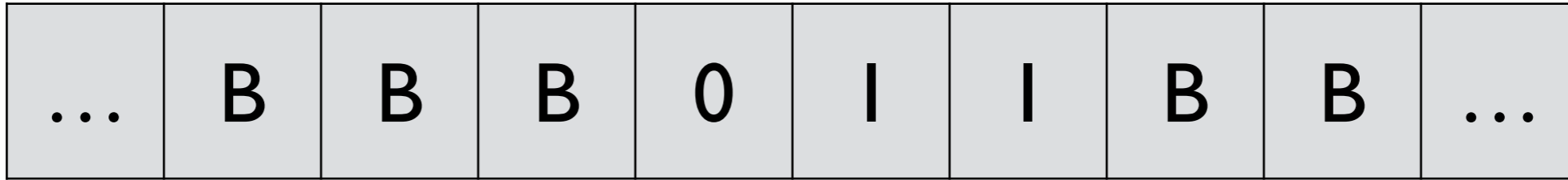
Begin a new cycle.

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



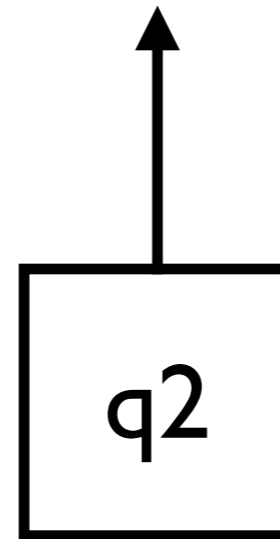
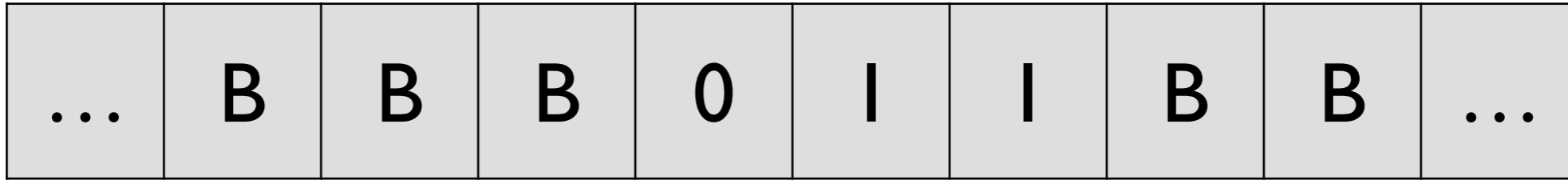
look for leftmost 1

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



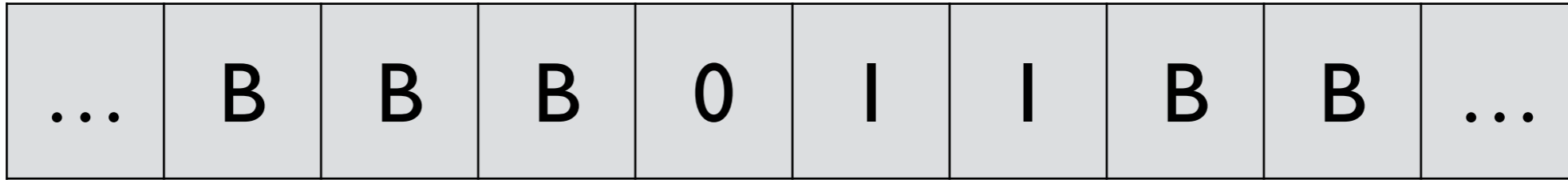
When found, enter q_2

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

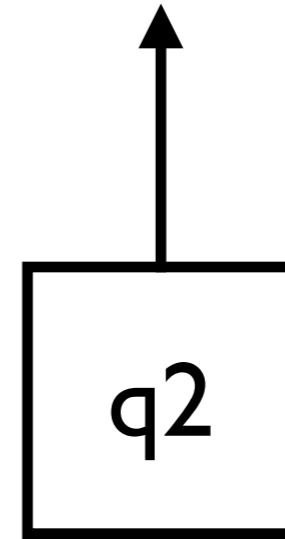


move right until it finds 0

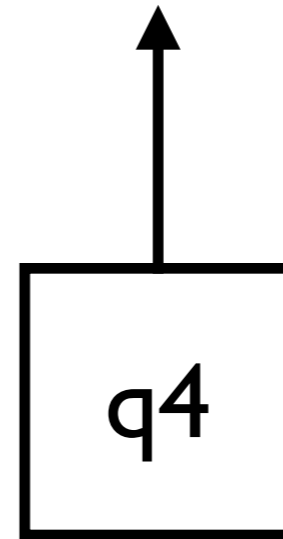
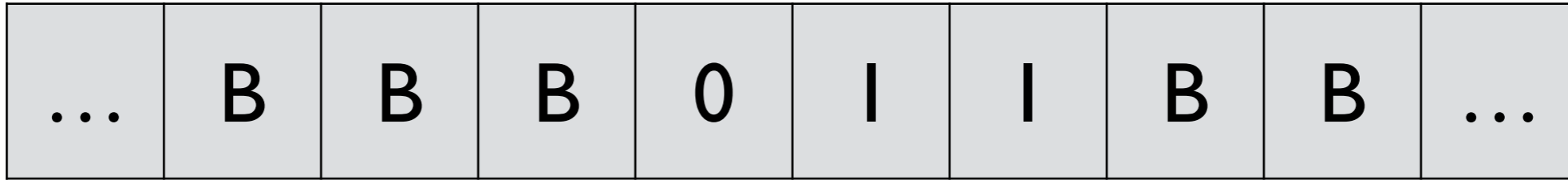
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



- No more 0's.
- All n 0's changed to 1
- $n+1$ 0's changed to B
- $m-(n+1)$ 0's on the tape
- replace all 1's by B and put one 0

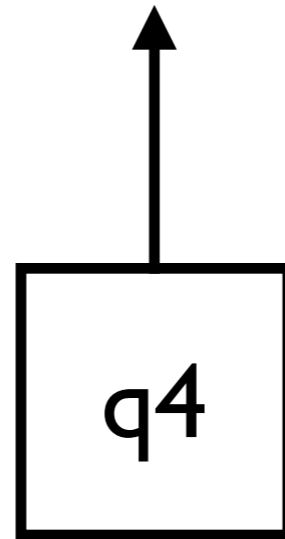
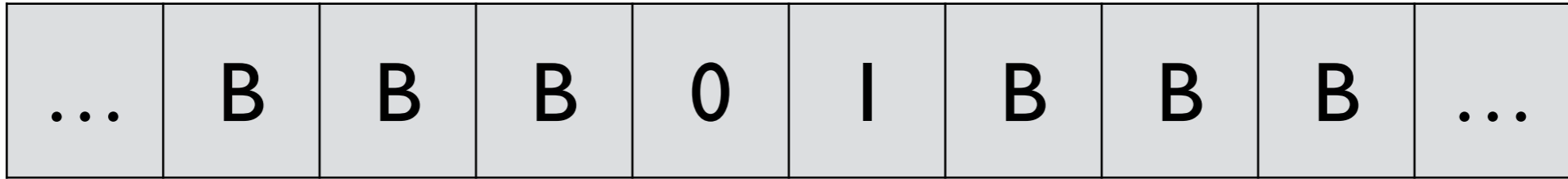


	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

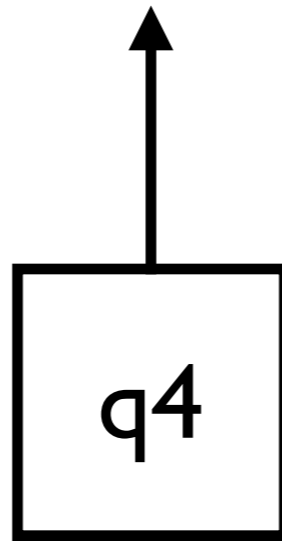
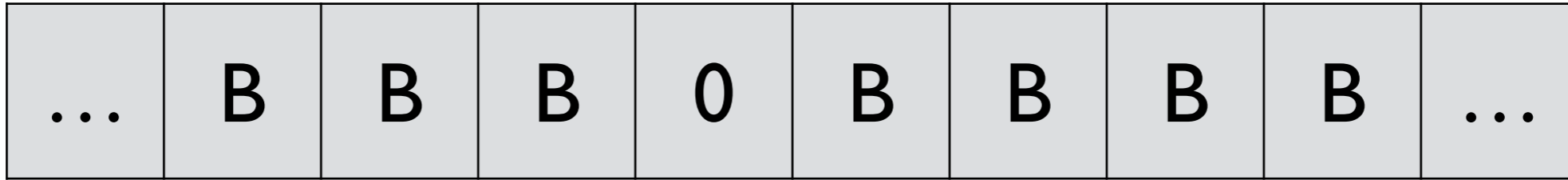


move left, changing 1 by B, until it finds B

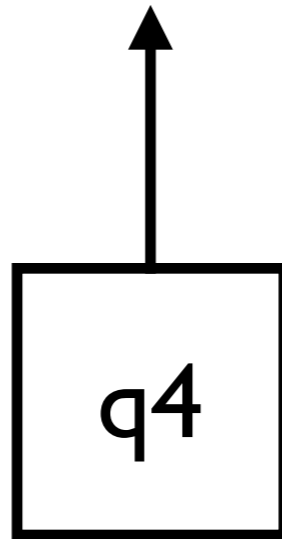
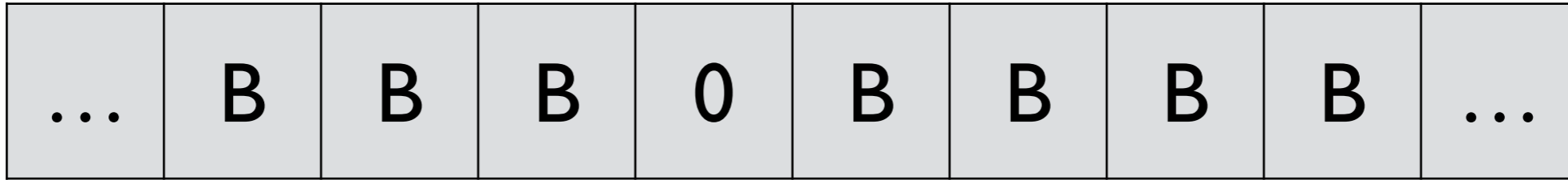
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

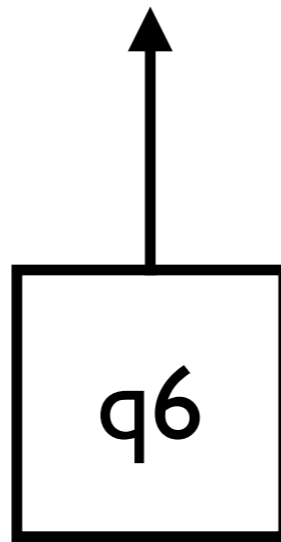
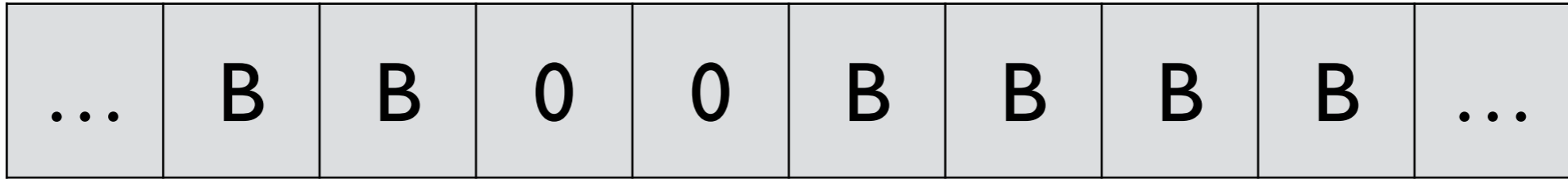


	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



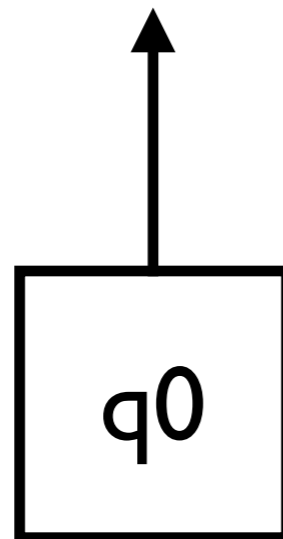
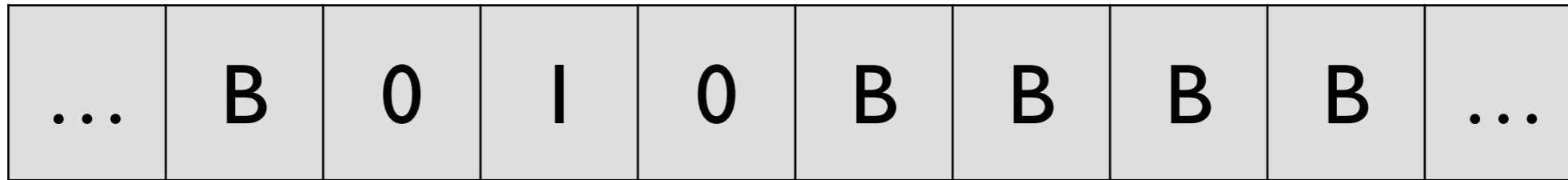
- change that B by 0
- enter the final state

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



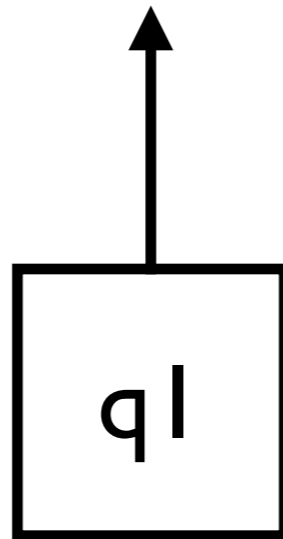
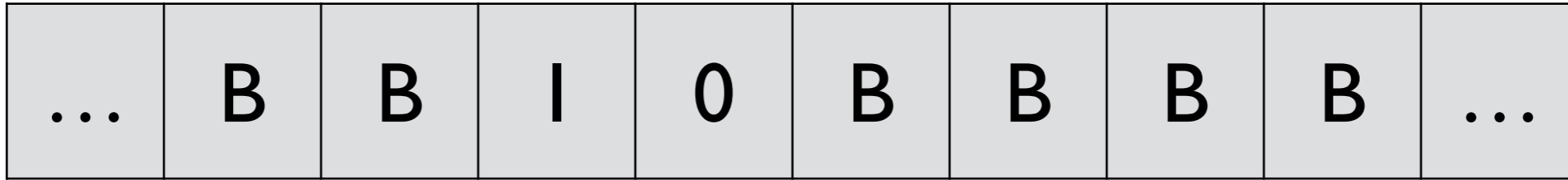
	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

e.g., $f(1, 1)$



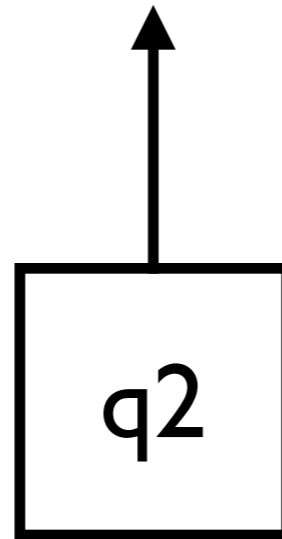
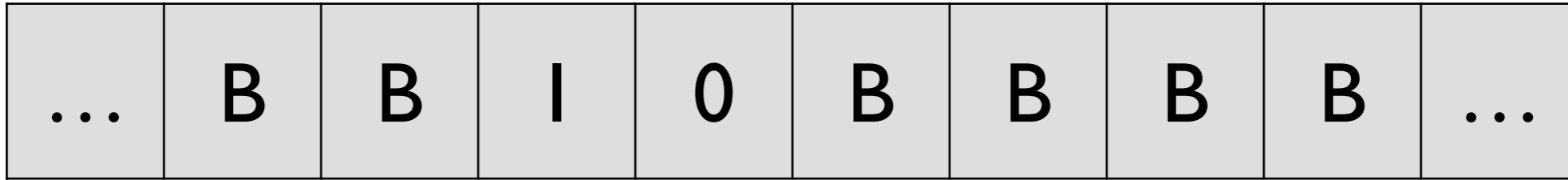
- change 0 by B
- enter q_1

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



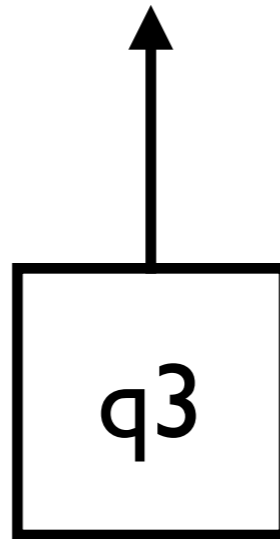
- look for the leftmost I
- when found, enter q2

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



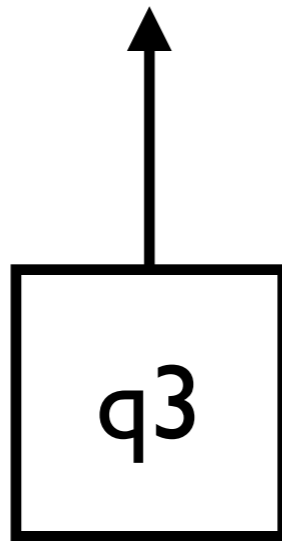
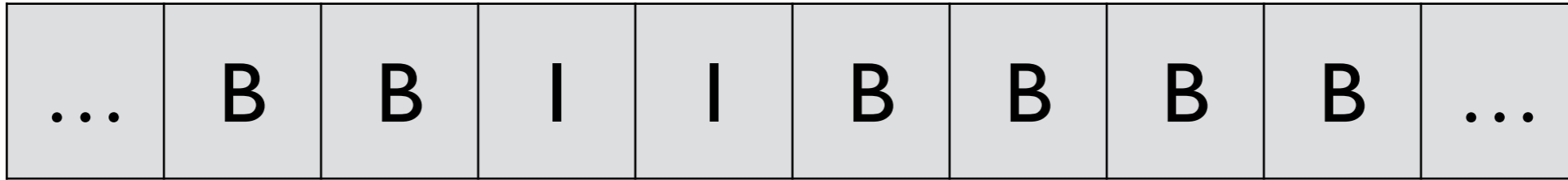
- move right until it finds 0
- when found, that 0 by 1
- enter q3

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



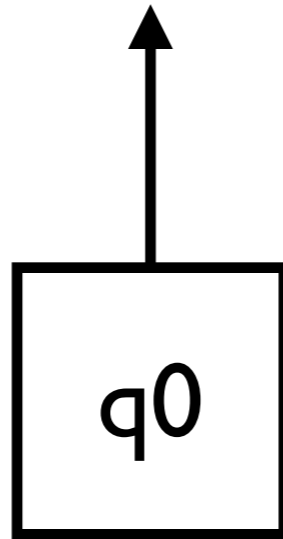
move left until it finds B

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



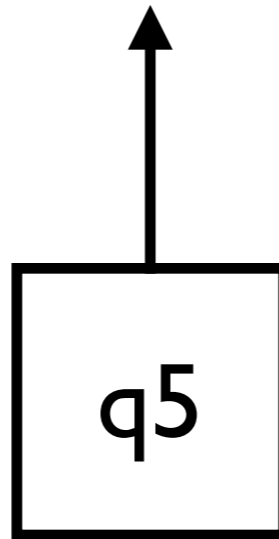
when B found, begin the cycle

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



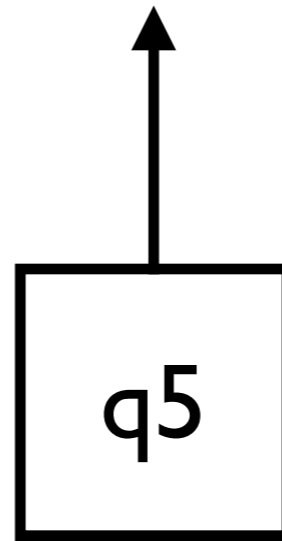
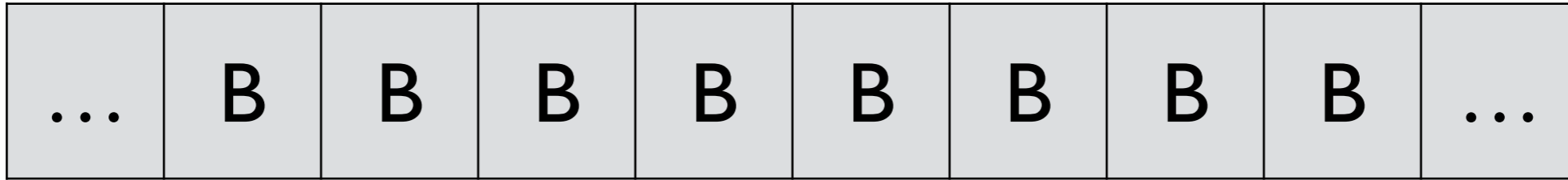
- cannot find 0 in q_0
- $n \geq m$
- replace I by B
- enter q_5

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



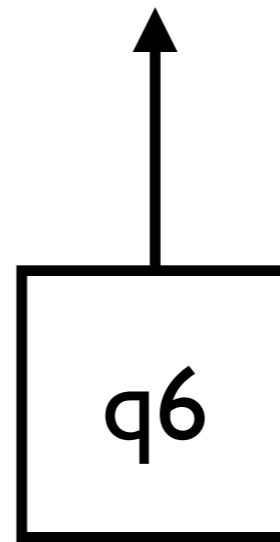
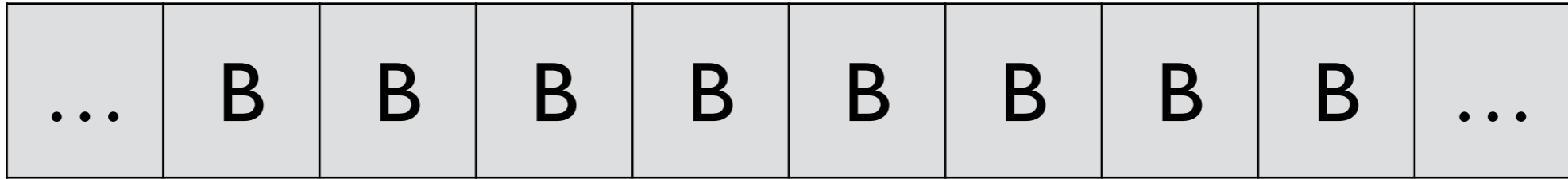
In q_5 , change all 0's and 1's to B

	0	1	B
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			



enter q6

	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

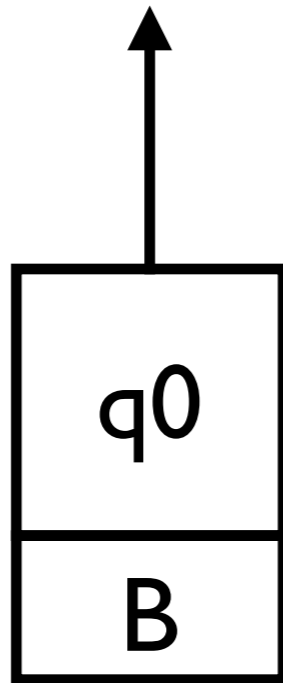
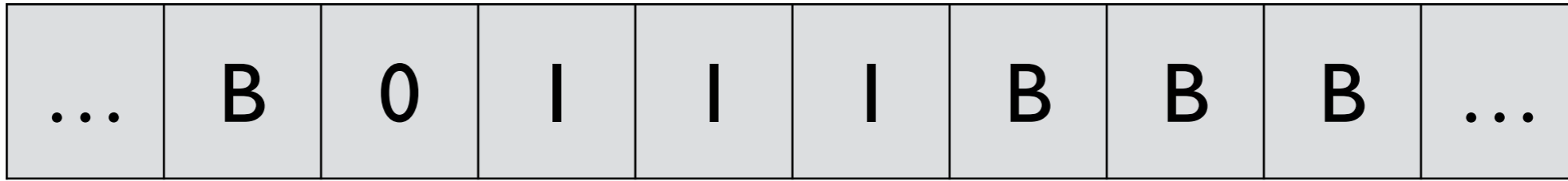


	0	1	<i>B</i>
q_0	(q_1, B, R)	(q_5, B, R)	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)
q_6			

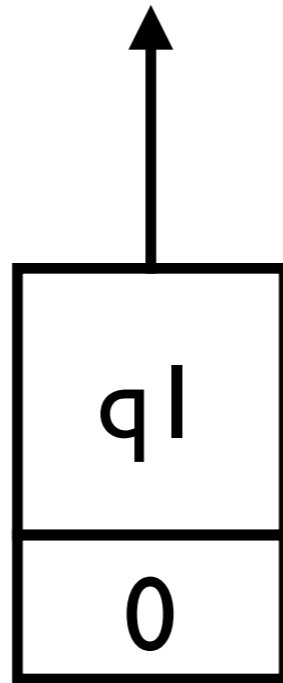
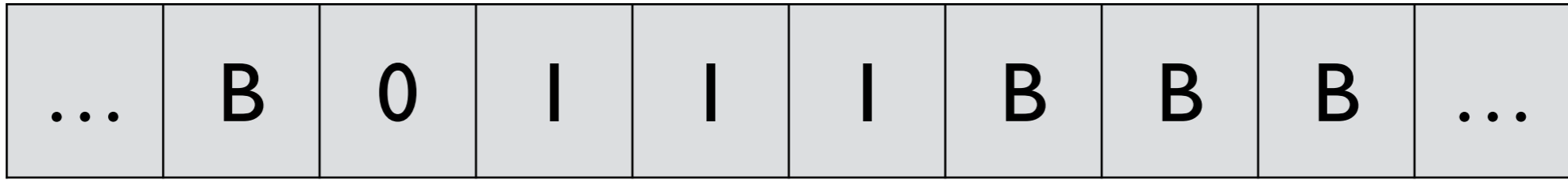
Example 5. Design a Turing machine that accepts $01^* + 10^*$.

$$M = (\{q_0, q_1\} \times \{0, 1, B\}, \{0, 1\}, \{0, 1, B\}, \delta, (q_0, B), B, \{(q_1, B)\})$$

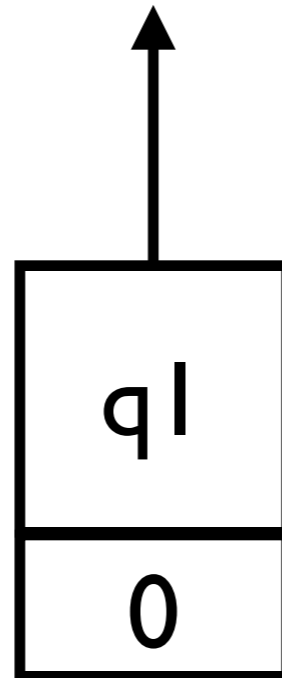
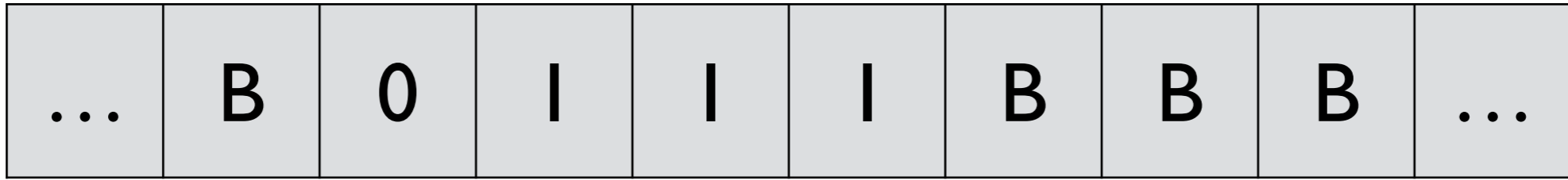
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



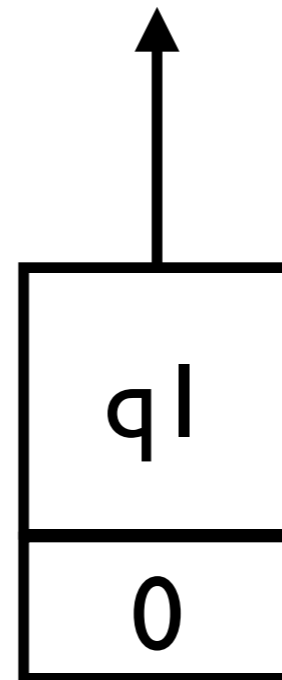
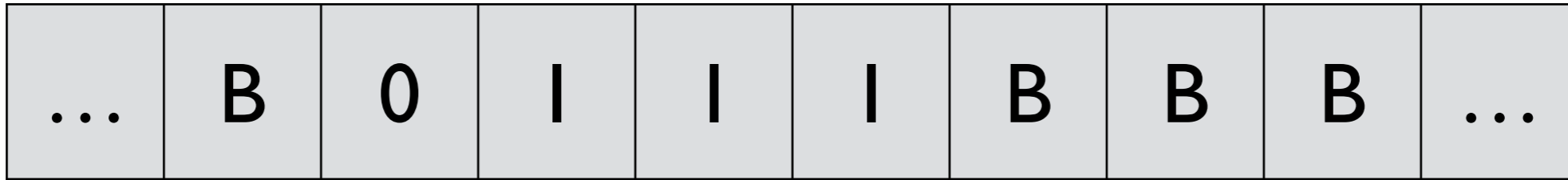
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



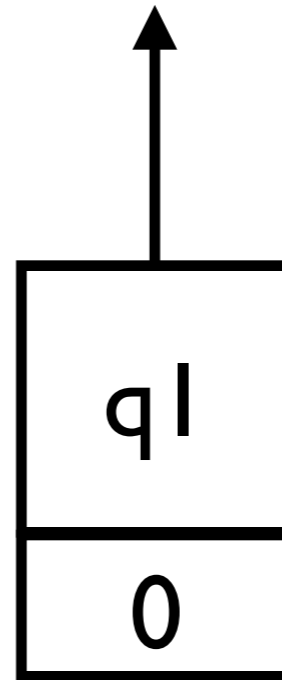
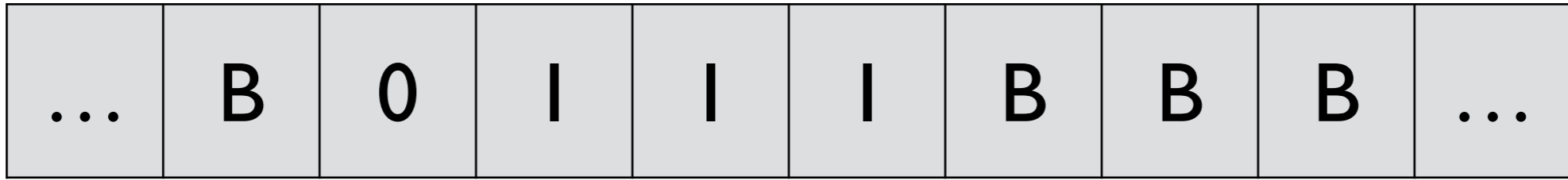
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



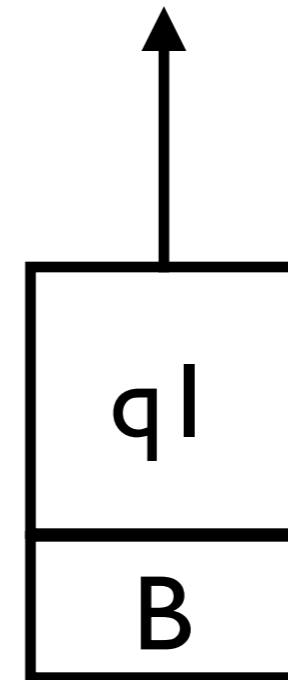
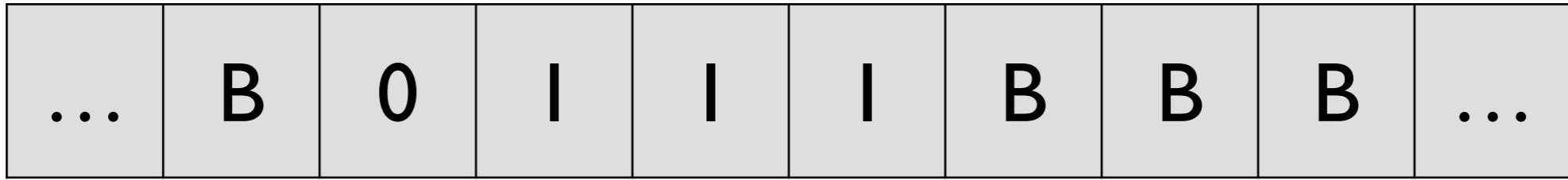
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



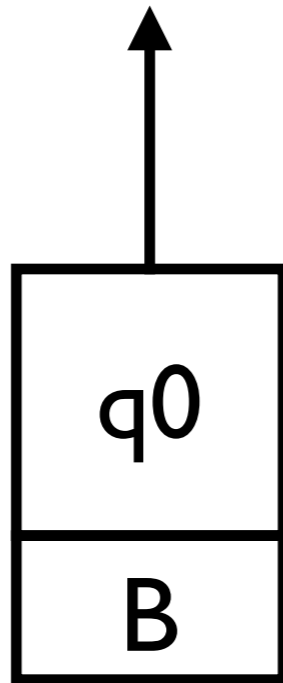
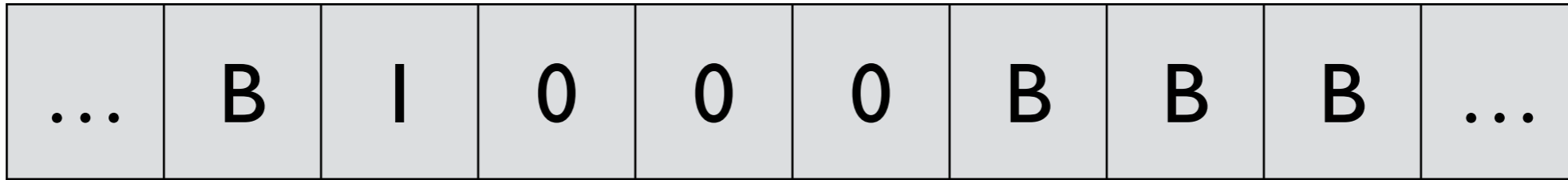
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



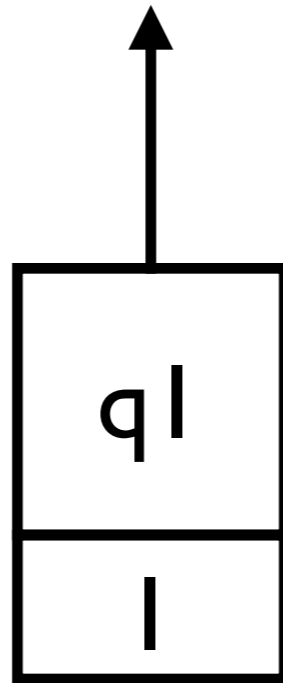
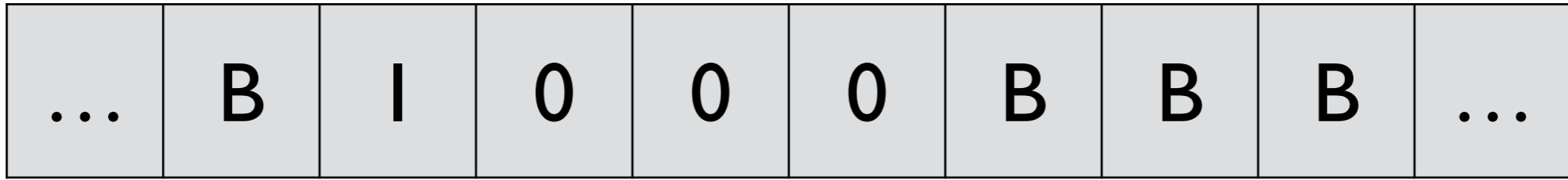
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



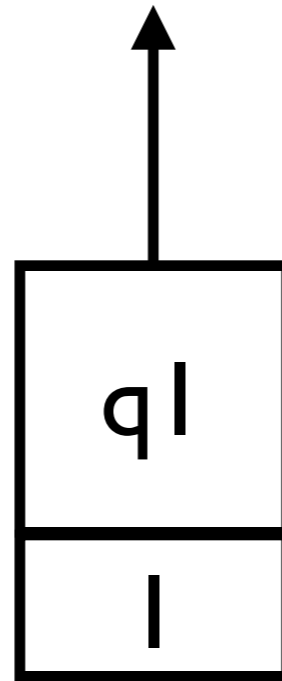
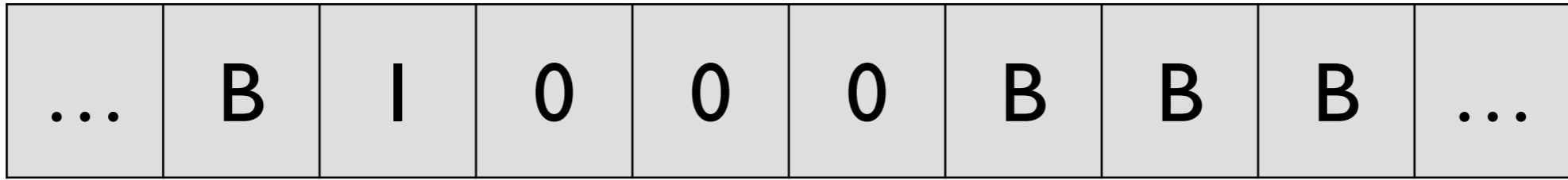
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



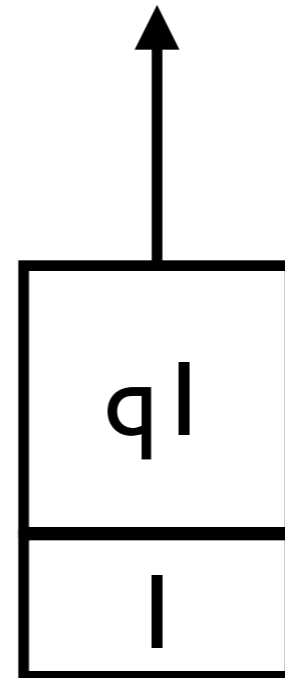
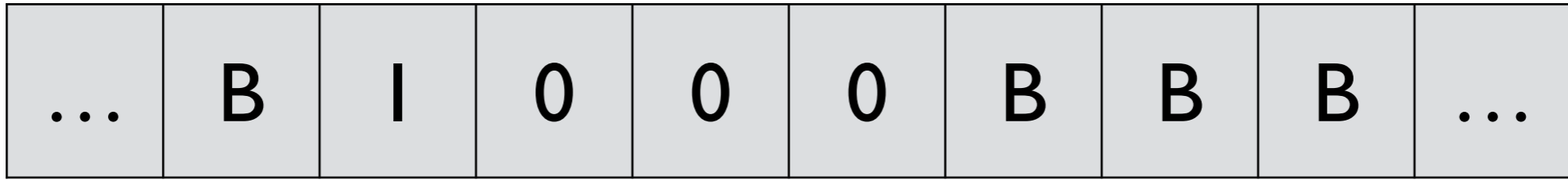
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



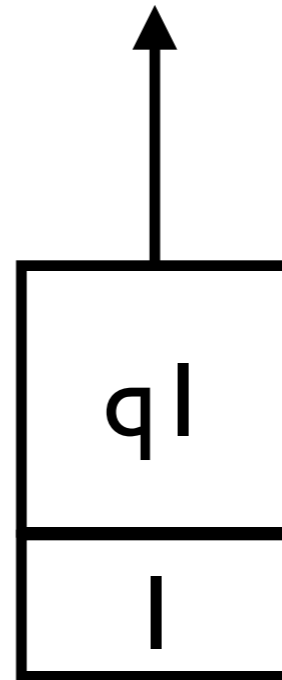
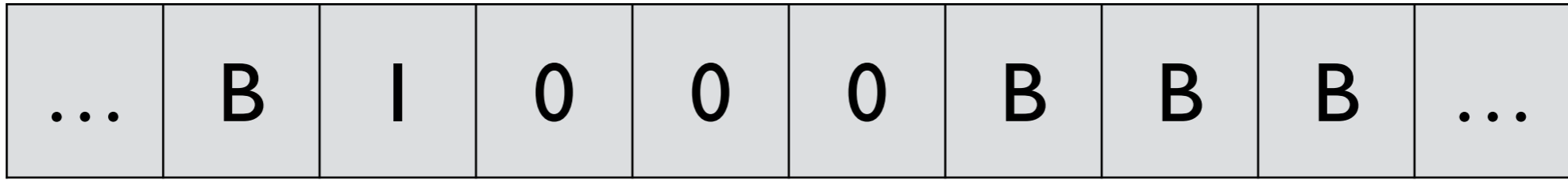
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



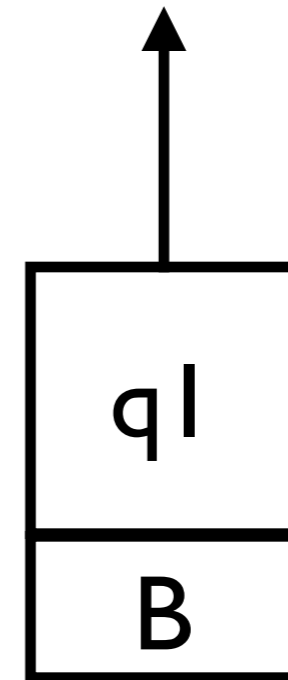
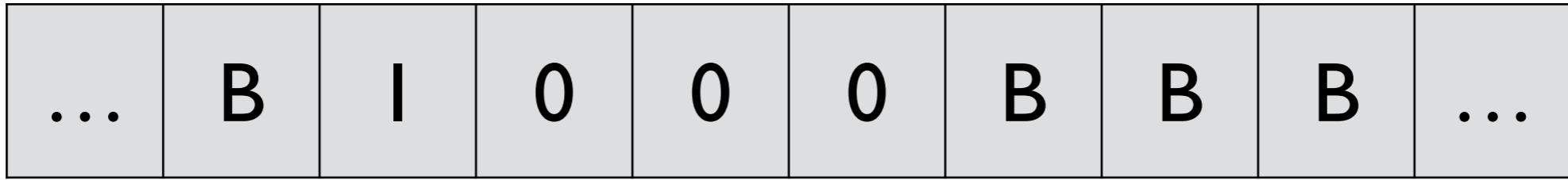
1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$



1. $\delta((q_0, B), a) = ((q_1, a), a, R)$ for $a = 0$ or $a = 1$
2. $\delta((q_1, a), \bar{a}) = ((q_1, a), \bar{a}, R)$
3. $\delta((q_1, a), B) = ((q_1, B), B, R)$

Example 6. Design a Turing machine that accepts $L = \{w cw \mid w \in \{0, 1\}^+\}$.

$$M = (Q, \Sigma, \Gamma, \delta, (q_1, B), (B, B), \{q_9, B\})$$

- $\{q_1, q_2, \dots, q_9\} \times \{0, 1, B\}$
- $\Gamma = \{B, *\} \times \{0, 1, c, B\}$
- $\Sigma = \{(B, 0), (B, 1), (B, c)\}$

$$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$$

$$\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$$

$$\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$$

$$\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$$

$$\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$$

$$\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$$

$$\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$$

$$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$$

$$\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$$

$$\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$$

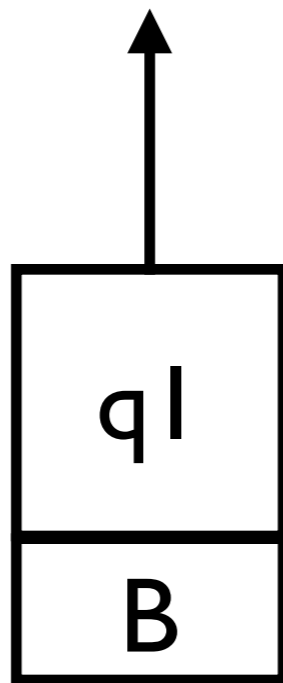
$$\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$$

$$\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$$

$$\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$$

$$\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$$

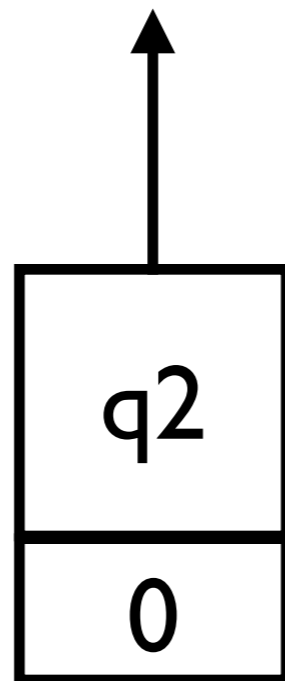
...	B	B	B	B	B	B	B	B	...
...	B	0	l	c	0	l	B	B	...



$$\begin{aligned}
\delta((q_1, B), (B, a)) &= ((q_2, a), (*, a), R) \\
\delta((q_2, a), (B, b)) &= ((q_2, a), (B, b), R) \\
\delta((q_2, a), (B, c)) &= ((q_3, a), (B, c), R) \\
\delta((q_3, a), (*, b)) &= ((q_3, a), (*, b), R) \\
\delta((q_3, a), (B, a)) &= ((q_4, B), (*, a), L) \\
\delta((q_4, B), (*, a)) &= ((q_4, B), (*, a), L) \\
\delta((q_4, B), (B, c)) &= ((q_5, B), (B, c), L)
\end{aligned}$$

$$\begin{aligned}
\delta((q_5, B), (B, a)) &= ((q_6, B), (B, a), L) \\
\delta((q_6, B), (B, a)) &= ((q_6, B), (B, a), L) \\
\delta((q_6, B), (*, a)) &= ((q_1, B), (*, a), R) \\
\delta((q_5, B), (*, a)) &= ((q_7, B), (*, a), R) \\
\delta((q_7, B), (B, c)) &= ((q_8, B), (B, c), R) \\
\delta((q_8, B), (*, a)) &= ((q_8, B), (*, a), R) \\
\delta((q_8, B), (B, B)) &= ((q_9, B), (B, B), R)
\end{aligned}$$

...	B	*	B	B	B	B	B	B	...
...	B	0		c	0		B	B	...

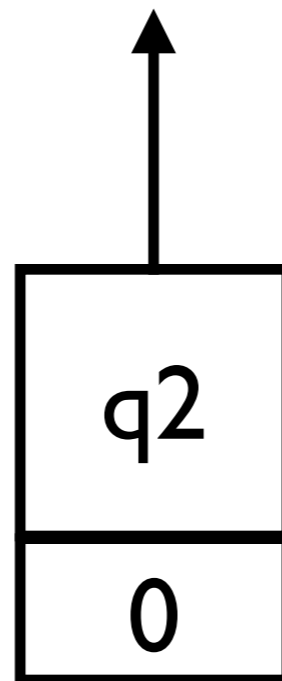


In q2, moves right, looking for c

$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

...	B	*	B	B	B	B	B	B	...
...	B	0	I	c	0	I	B	B	...

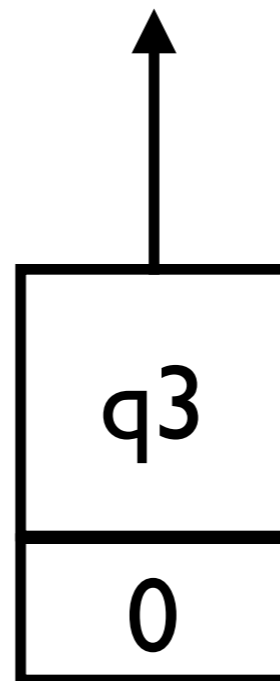


- When found,
- enter q3
 - continue right

$$\begin{aligned} \delta((q_1, B), (B, a)) &= ((q_2, a), (*, a), R) \\ \delta((q_2, a), (B, b)) &= ((q_2, a), (B, b), R) \\ \delta((q_2, a), (B, c)) &= ((q_3, a), (B, c), R) \\ \delta((q_3, a), (*, b)) &= ((q_3, a), (*, b), R) \\ \delta((q_3, a), (B, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (*, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (B, c)) &= ((q_5, B), (B, c), L) \end{aligned}$$

$$\begin{aligned} \delta((q_5, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (*, a)) &= ((q_1, B), (*, a), R) \\ \delta((q_5, B), (*, a)) &= ((q_7, B), (*, a), R) \\ \delta((q_7, B), (B, c)) &= ((q_8, B), (B, c), R) \\ \delta((q_8, B), (*, a)) &= ((q_8, B), (*, a), R) \\ \delta((q_8, B), (B, B)) &= ((q_9, B), (B, B), R) \end{aligned}$$

...	B	*	B	B	B	B	B	B	...
...	B	0	l	c	0	l	B	B	...

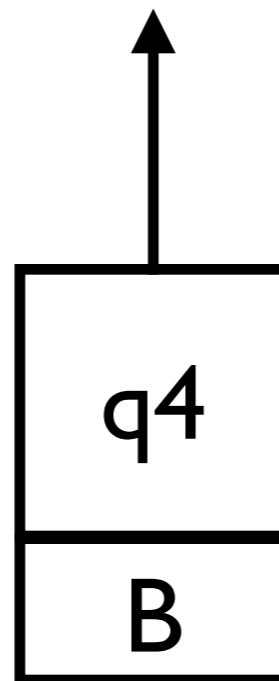


In q_3 ,
look for the first
unchecked symbol

$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

...	B	*	B	B	*	B	B	B	...
...	B	0	l	c	0	l	B	B	...

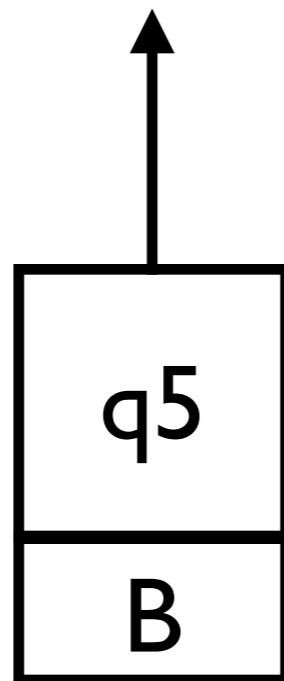


- In q_4 , move left until it finds c
- When found, enter q_5

$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

...	B	*	B	B	*	B	B	B	...
...	B	0	l	c	0	l	B	B	...

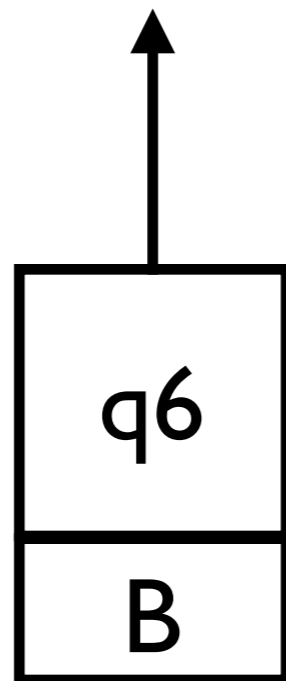


- If there is some unchecked symbol, enter q6

$$\begin{aligned} \delta((q_1, B), (B, a)) &= ((q_2, a), (*, a), R) \\ \delta((q_2, a), (B, b)) &= ((q_2, a), (B, b), R) \\ \delta((q_2, a), (B, c)) &= ((q_3, a), (B, c), R) \\ \delta((q_3, a), (*, b)) &= ((q_3, a), (*, b), R) \\ \delta((q_3, a), (B, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (*, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (B, c)) &= ((q_5, B), (B, c), L) \end{aligned}$$

$$\begin{aligned} \delta((q_5, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (*, a)) &= ((q_1, B), (*, a), R) \\ \delta((q_5, B), (*, a)) &= ((q_7, B), (*, a), R) \\ \delta((q_7, B), (B, c)) &= ((q_8, B), (B, c), R) \\ \delta((q_8, B), (*, a)) &= ((q_8, B), (*, a), R) \\ \delta((q_8, B), (B, B)) &= ((q_9, B), (B, B), R) \end{aligned}$$

...	B	*	B	B	*	B	B	B	...
...	B	0	l	c	0	l	B	B	...

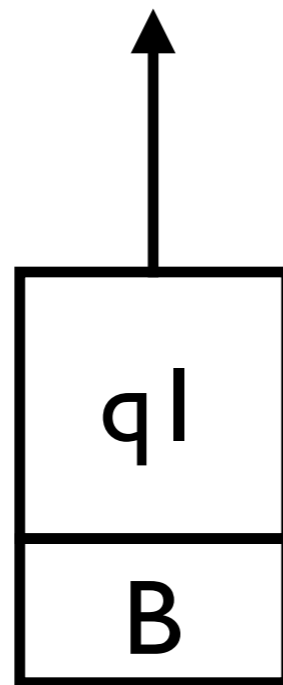


- In q_6 , move left and look for the first unchecked symbol

$$\begin{aligned} \delta((q_1, B), (B, a)) &= ((q_2, a), (*, a), R) \\ \delta((q_2, a), (B, b)) &= ((q_2, a), (B, b), R) \\ \delta((q_2, a), (B, c)) &= ((q_3, a), (B, c), R) \\ \delta((q_3, a), (*, b)) &= ((q_3, a), (*, b), R) \\ \delta((q_3, a), (B, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (*, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (B, c)) &= ((q_5, B), (B, c), L) \end{aligned}$$

$$\begin{aligned} \delta((q_5, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (*, a)) &= ((q_1, B), (*, a), R) \\ \delta((q_5, B), (*, a)) &= ((q_7, B), (*, a), R) \\ \delta((q_7, B), (B, c)) &= ((q_8, B), (B, c), R) \\ \delta((q_8, B), (*, a)) &= ((q_8, B), (*, a), R) \\ \delta((q_8, B), (B, B)) &= ((q_9, B), (B, B), R) \end{aligned}$$

...	B	*	B	B	*	B	B	B	...
...	B	0	l	c	0	l	B	B	...

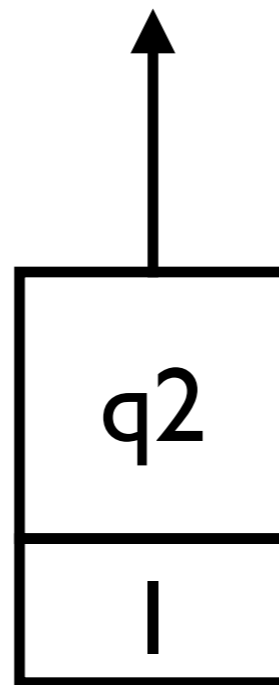


- Repeat the cycle

$$\begin{aligned} \delta((q_1, B), (B, a)) &= ((q_2, a), (*, a), R) \\ \delta((q_2, a), (B, b)) &= ((q_2, a), (B, b), R) \\ \delta((q_2, a), (B, c)) &= ((q_3, a), (B, c), R) \\ \delta((q_3, a), (*, b)) &= ((q_3, a), (*, b), R) \\ \delta((q_3, a), (B, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (*, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (B, c)) &= ((q_5, B), (B, c), L) \end{aligned}$$

$$\begin{aligned} \delta((q_5, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (*, a)) &= ((q_1, B), (*, a), R) \\ \delta((q_5, B), (*, a)) &= ((q_7, B), (*, a), R) \\ \delta((q_7, B), (B, c)) &= ((q_8, B), (B, c), R) \\ \delta((q_8, B), (*, a)) &= ((q_8, B), (*, a), R) \\ \delta((q_8, B), (B, B)) &= ((q_9, B), (B, B), R) \end{aligned}$$

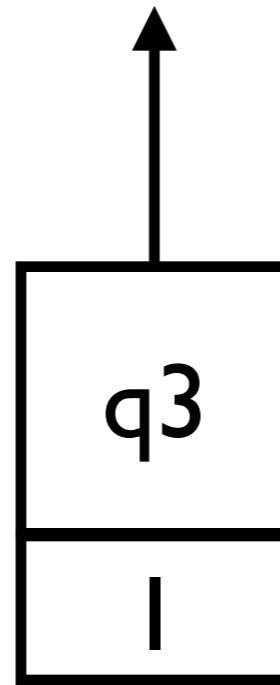
...	B	*	*	B	*	B	B	B	...
...	B	0	1	c	0	1	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

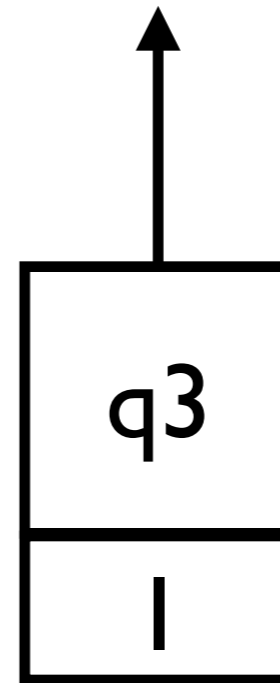
...	B	*	*	B	*	B	B	B	...
...	B	0	l	c	0	l	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

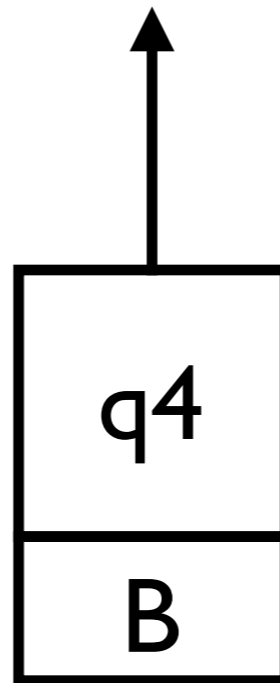
...	B	*	*	B	*	B	B	B	...
...	B	0	l	c	0	l	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

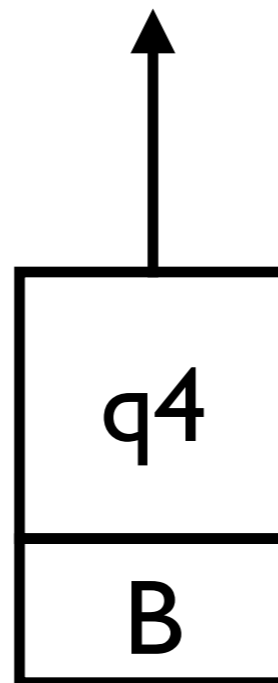
...	B	*	*	B	*	*	B	B	...
...	B	0	1	c	0	1	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

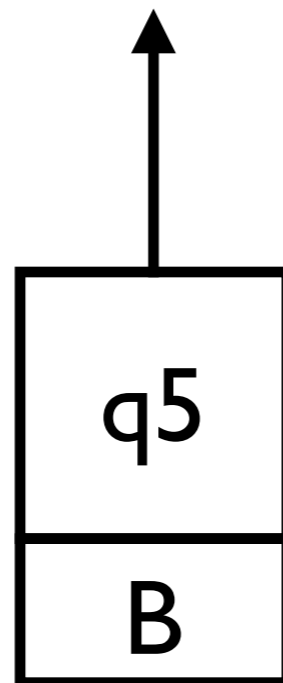
...	B	*	*	B	*	*	B	B	...
...	B	0	1	c	0	1	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

...	B	*	*	B	*	*	B	B	...
...	B	0	l	c	0	l	B	B	...

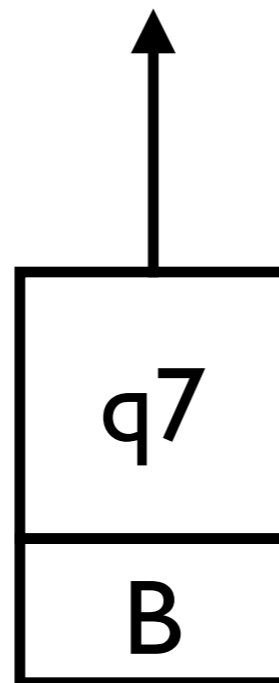


- If every symbols are checked, move right and enter q7

$$\begin{aligned} \delta((q_1, B), (B, a)) &= ((q_2, a), (*, a), R) \\ \delta((q_2, a), (B, b)) &= ((q_2, a), (B, b), R) \\ \delta((q_2, a), (B, c)) &= ((q_3, a), (B, c), R) \\ \delta((q_3, a), (*, b)) &= ((q_3, a), (*, b), R) \\ \delta((q_3, a), (B, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (*, a)) &= ((q_4, B), (*, a), L) \\ \delta((q_4, B), (B, c)) &= ((q_5, B), (B, c), L) \end{aligned}$$

$$\begin{aligned} \delta((q_5, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (B, a)) &= ((q_6, B), (B, a), L) \\ \delta((q_6, B), (*, a)) &= ((q_1, B), (*, a), R) \\ \delta((q_5, B), (*, a)) &= ((q_7, B), (*, a), R) \\ \delta((q_7, B), (B, c)) &= ((q_8, B), (B, c), R) \\ \delta((q_8, B), (*, a)) &= ((q_8, B), (*, a), R) \\ \delta((q_8, B), (B, B)) &= ((q_9, B), (B, B), R) \end{aligned}$$

...	B	*	*	B	*	*	B	B	...
...	B	0	1	c	0	1	B	B	...

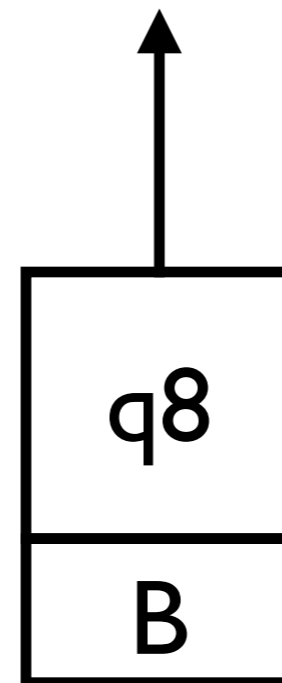


- If c is found, enter q8

$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

...	B	*	*	B	*	*	B	B	...
...	B	0	1	c	0	1	B	B	...

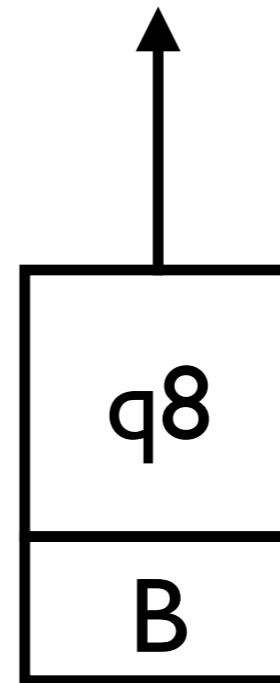


- move right until it finds B

$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

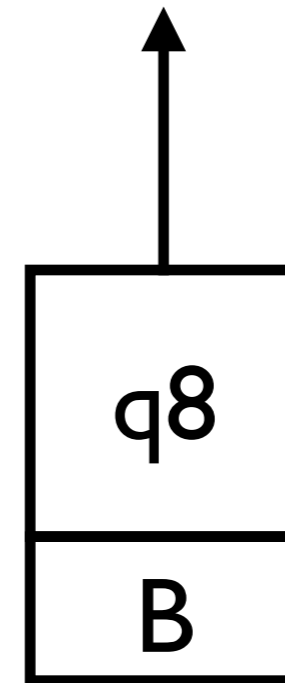
...	B	*	*	B	*	*	B	B	...
...	B	0	l	c	0	l	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

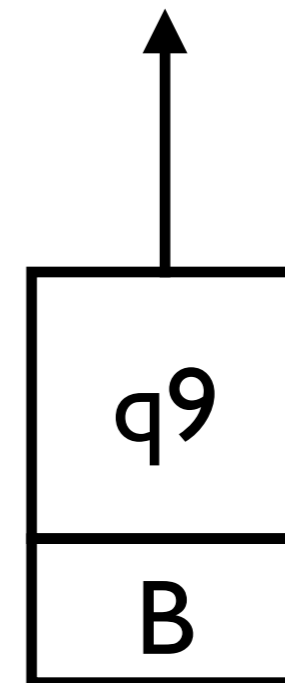
...	B	*	*	B	*	*	B	B	...
...	B	0	l	c	0	l	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$

...	B	*	*	B	*	*	B	B	...
...	B	0	l	c	0	l	B	B	...



$\delta((q_1, B), (B, a)) = ((q_2, a), (*, a), R)$
 $\delta((q_2, a), (B, b)) = ((q_2, a), (B, b), R)$
 $\delta((q_2, a), (B, c)) = ((q_3, a), (B, c), R)$
 $\delta((q_3, a), (*, b)) = ((q_3, a), (*, b), R)$
 $\delta((q_3, a), (B, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (*, a)) = ((q_4, B), (*, a), L)$
 $\delta((q_4, B), (B, c)) = ((q_5, B), (B, c), L)$

$\delta((q_5, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (B, a)) = ((q_6, B), (B, a), L)$
 $\delta((q_6, B), (*, a)) = ((q_1, B), (*, a), R)$
 $\delta((q_5, B), (*, a)) = ((q_7, B), (*, a), R)$
 $\delta((q_7, B), (B, c)) = ((q_8, B), (B, c), R)$
 $\delta((q_8, B), (*, a)) = ((q_8, B), (*, a), R)$
 $\delta((q_8, B), (B, B)) = ((q_9, B), (B, B), R)$