## COSE212: Programming Languages

## Lecture 11 - Automatic Type Inference (2)

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## Finding a Solution of Type Equations

Find values for the type variables that make all the equations true.


| Equations |  |
| :--- | :--- |
|  |  |
| $\boldsymbol{t}_{\mathbf{0}}=\boldsymbol{t}_{\boldsymbol{f}} \rightarrow \boldsymbol{t}_{\mathbf{1}}$ | Solution |
| $\boldsymbol{t}_{\mathbf{1}}=$ t $\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{2}}$ | $\boldsymbol{t}_{\mathbf{1}}=$ (int $\rightarrow$ int $) \rightarrow$ (int $\rightarrow$ int $)$ |
| $\boldsymbol{t}_{\mathbf{3}}=$ int | $\boldsymbol{t}_{\mathbf{2}}=$ int |
| $\boldsymbol{t}_{\mathbf{4}}=$ int | $\boldsymbol{t}_{\mathbf{3}}=$ int |
| $\boldsymbol{t}_{\mathbf{2}}=$ int | $\boldsymbol{t}_{\mathbf{4}}=$ int |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow \boldsymbol{t}_{\mathbf{3}}$ | $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow$ int |
| $\boldsymbol{t}_{\boldsymbol{f}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{4}}$ | $\boldsymbol{t}_{\boldsymbol{x}}=$ int |

Such a solution can be found by the unification algorithm.

## Unification Algorithm: Example 1

The calculation is split into equations to be solved and substitution found so far. Initially, the substitution is empty:

| Equations | Substitution |
| ---: | :--- | :--- |
| $\boldsymbol{t}_{\mathbf{0}}=\boldsymbol{t}_{\boldsymbol{f}} \rightarrow \boldsymbol{t}_{1}$ |  |
| $\boldsymbol{t}_{\mathbf{1}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{2}}$ |  |
| $\boldsymbol{t}_{\mathbf{3}}=$ int |  |
| $\boldsymbol{t}_{\mathbf{4}}=$ int |  |
| $\boldsymbol{t}_{\mathbf{2}}=$ int |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow \boldsymbol{t}_{\boldsymbol{3}}$ |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{4}}$ |  |

## Unification Algorithm: Example 1

Consider each equation in turn. If the equation's left-hand side is a variable, move it to the substitution:

| Equations | Substitution |
| :--- | :--- |
| $\boldsymbol{t}_{\mathbf{1}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{2}}$ | $\boldsymbol{t}_{\mathbf{0}}=\boldsymbol{t}_{\boldsymbol{f}} \rightarrow \boldsymbol{t}_{\mathbf{1}}$ |
| $\boldsymbol{t}_{\mathbf{3}}=$ int |  |
| $\boldsymbol{t}_{\boldsymbol{4}}=$ int |  |
| $\boldsymbol{t}_{\mathbf{2}}=$ int |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow \boldsymbol{t}_{\mathbf{3}}$ |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\boldsymbol{4}}$ |  |

## Unification Algorithm: Example 1

Move the next equation to the substitution and propagate the information to the existing substitution (i.e., substitute the right-hand side for each occurrence of $\boldsymbol{t}_{1}$ ):

| Equations | Substitution |
| :--- | :--- |
| $\boldsymbol{t}_{\mathbf{3}}=$ int | $\boldsymbol{t}_{\mathbf{0}}=\boldsymbol{t}_{\boldsymbol{f}} \rightarrow\left(\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{2}}\right)$ |
| $\boldsymbol{t}_{\boldsymbol{4}}=$ int | $\boldsymbol{t}_{1}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\mathbf{2}}$ |
| $\boldsymbol{t}_{\mathbf{2}}=$ int |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow \boldsymbol{t}_{\mathbf{3}}$ |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{\boldsymbol{4}}$ |  |

## Unification Algorithm: Example 1

Same for the next three equations:

| Equations | Substitution |
| :---: | :---: |
| $\boldsymbol{t}_{\boldsymbol{4}}=$ int | $t_{0}=t_{f} \rightarrow\left(t_{x} \rightarrow t_{2}\right)$ |
| $\boldsymbol{t}_{2}=$ int | $t_{1}=t_{x} \rightarrow t_{2}$ |
| $t_{f}=$ int $\rightarrow t_{3}$ | $\boldsymbol{t}_{3}=\mathrm{int}$ |
| $t_{f}=t_{x} \rightarrow t_{4}$ |  |
| Equations | Substitution |
| $\boldsymbol{t}_{\mathbf{2}}=\mathrm{int}$ | $t_{0}=t_{f} \rightarrow\left(t_{x} \rightarrow t_{2}\right)$ |
| $t_{f}=\mathrm{int} \rightarrow t_{3}$ | $t_{1}=t_{x} \rightarrow t_{2}$ |
| $t_{f}=t_{x} \rightarrow t_{4}$ | $\begin{aligned} & \boldsymbol{t}_{\mathbf{3}}=\text { int } \\ & \boldsymbol{t}_{\mathbf{4}}=\text { int } \end{aligned}$ |
| Equations | Substitution |
| $t_{f}=$ int $\rightarrow t_{3}$ | $t_{0}=t_{f} \rightarrow\left(t_{x} \rightarrow \mathrm{int}\right)$ |
| $t_{f}=t_{x} \rightarrow t_{4}$ | $t_{1}=t_{x} \rightarrow \mathrm{int}$ |
|  | $\boldsymbol{t}_{\mathbf{3}}=\mathrm{int}$ |
|  | $\boldsymbol{t}_{4}=\mathrm{int}$ |
|  | $\boldsymbol{t}_{\mathbf{2}}=\mathrm{int}$ |

## Unification Algorithm: Example 1

Consider the next equation $\boldsymbol{t}_{f}=\mathrm{int} \rightarrow \boldsymbol{t}_{\mathbf{3}}$. The equation contains $\boldsymbol{t}_{\mathbf{3}}$, which is already bound to int in the substitution. Substitute int for $t_{3}$ in the equation. This is called applying the substitution to the equation.

| Equations | Substitution |
| :--- | :--- |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow$ int | $\boldsymbol{t}_{\mathbf{0}}=\boldsymbol{t}_{\boldsymbol{f}} \rightarrow\left(\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \mathrm{int}\right)$ |
| $\boldsymbol{t}_{\boldsymbol{f}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \boldsymbol{t}_{4}$ | $\boldsymbol{t}_{\mathbf{1}}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow$ int |
| $\boldsymbol{t}_{3}=$ int |  |
| $\boldsymbol{t}_{\mathbf{4}}=$ int |  |
| $\boldsymbol{t}_{\mathbf{2}}=$ int |  |

Move the resulting equation to the substitution and update it.

| Equations | Substitution |
| :---: | :---: |
| $t_{f}=t_{x} \rightarrow t_{4}$ | $\begin{aligned} \boldsymbol{t}_{\mathbf{0}} & =(\text { int } \rightarrow \text { int }) \rightarrow\left(\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \mathrm{int}\right) \\ \boldsymbol{t}_{\mathbf{1}} & =\boldsymbol{t}_{\boldsymbol{x}} \rightarrow \text { int } \\ \boldsymbol{t}_{3} & =\text { int } \\ \boldsymbol{t}_{\mathbf{4}} & =\text { int } \\ \boldsymbol{t}_{\mathbf{2}} & =\text { int } \\ \boldsymbol{t}_{\boldsymbol{f}} & =\text { int } \rightarrow \text { int } \end{aligned}$ |

## Unification Algorithm: Example 1

Apply the substitution to the equation:

| Equations |  |
| :--- | :--- |
| int $\rightarrow$ int $=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow$ int | $\boldsymbol{t}_{\mathbf{0}}=$ (int $\rightarrow$ int $) \rightarrow\left(t_{x} \rightarrow \mathrm{int}\right)$ |
|  | $\boldsymbol{t}_{1}=\boldsymbol{t}_{\boldsymbol{x}} \rightarrow$ int |
| $\boldsymbol{t}_{3}=$ int |  |
|  | $\boldsymbol{t}_{\mathbf{4}}=$ int |
| $\boldsymbol{t}_{2}=$ int |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow$ int |  |

If neither side of the equation is a variable, simplify the equation by yielding two new equations:

| Equations | Substitution |
| :---: | :---: |
| int $=\boldsymbol{t}_{\boldsymbol{x}}$ | $t_{0}=($ int $\rightarrow$ int $) \rightarrow\left(t_{x} \rightarrow\right.$ int $)$ |
| int $=$ int | $t_{1}=t_{x} \rightarrow \mathrm{int}$ |
|  | $\boldsymbol{t}_{3}=\mathrm{int}$ |
|  | $\boldsymbol{t}_{\boldsymbol{4}}=\mathrm{int}$ |
|  | $\boldsymbol{t}_{2}=\mathrm{int}$ |
|  | $\boldsymbol{t}_{\boldsymbol{f}}=\mathrm{int} \rightarrow$ int |

## Unification Algorithm: Example 1

Switch the sides of the first equation and move it to the substitution:

| Equations | Substitution |
| :---: | :---: |
| int $=$ int | $\begin{aligned} & \left.\boldsymbol{t}_{\mathbf{0}}=\text { (int } \rightarrow \mathrm{int}\right) \rightarrow(\mathrm{int} \rightarrow \mathrm{int}) \\ & \boldsymbol{t}_{\mathbf{1}}=\text { int } \rightarrow \text { int } \\ & \boldsymbol{t}_{3}=\text { int } \\ & \boldsymbol{t}_{\mathbf{4}}=\text { int } \\ & \boldsymbol{t}_{\mathbf{2}}=\text { int } \\ & \boldsymbol{t}_{\boldsymbol{f}}=\text { int } \rightarrow \text { int } \\ & \boldsymbol{t}_{\boldsymbol{x}}=\text { int } \end{aligned}$ |

The final substitution is the solution of the original equations.

## Unification Algorithm

For each equation in turn,
(1) Apply the current substitituion to the equation.
(2) If the left-hand side is a variable, move it to the substitution and substitute the right-hand side for each occurrence of the variable in the substitution. (If the right-hand side is a variable, switch the sides and do the same thing).
Basically, the algorithm follows the two steps. Two execptions: If neither side is a variable, simplify the equation, which eventually generates an equation whose left- or right-hand side is a variable. If the equation is always true, discard it.

## Unification Algorithm: Example 2



$$
\begin{aligned}
\boldsymbol{t}_{\mathbf{0}} & =\boldsymbol{t}_{\boldsymbol{f}} \rightarrow \boldsymbol{t}_{1} \\
\boldsymbol{t}_{\boldsymbol{f}} & =\text { int } \rightarrow \boldsymbol{t}_{1}
\end{aligned}
$$

## Unification Algorithm: Example 2

(1)

| Equations | Substitution |
| :---: | :---: |
| $t_{0}=\boldsymbol{t}_{f} \rightarrow \boldsymbol{t}_{1}$ |  |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow \boldsymbol{t}_{1}$ |  |

(2)

| Equations | Substitution |
| :---: | :---: |
| $\boldsymbol{t}_{\boldsymbol{f}}=$ int $\rightarrow \boldsymbol{t}_{\mathbf{1}}$ | $\boldsymbol{t}_{\mathbf{0}}=\boldsymbol{t}_{\boldsymbol{f}} \rightarrow \boldsymbol{t}_{\mathbf{1}}$ |

(3)

| Equations | Substitution |
| :---: | :---: |
|  | $t_{0}=\left(\operatorname{int} \rightarrow t_{1}\right) \rightarrow \boldsymbol{t}_{1}$ |
|  | $t_{f}=$ int $\rightarrow t_{1}$ |

The type is polymorphic in $\boldsymbol{t}_{\mathbf{1}}$.

## Unification Algorithm: Example 3



## Unification Algorithm: Example 4



## Exercises

For each following expression, perform the type inference and find its type, or determine that no such type exists.
(1) let $x=4$ in ( $x 3$ )
(2) let $f=\operatorname{proc}(z) z$ in $\operatorname{proc}(x)((f x)-1)$
(3) let $p=$ iszero 1 in if $p$ then 88 else 99
(9) let $f=\operatorname{proc}(x) x$ in if $(f($ iszero 0$))$ then $(f 11)$ else $(f 22)$

## Summary

Automatic type inference:

- derive type equations from the program text, and
- solve the equations by unification.

