AAA616: Program Analysis Operational Semantics

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Plan

- Big-step operational semantics for While
- Small-step operational semantics for While
- Implementing Interpreters

Syntax vs. Semantics

A programming language is defined with syntax and semantics.

- The syntax is concerned with the grammatical structure of programs.
 - Context-free grammar
- The semantics is concerned with the meaning of grammatically correct programs.
 - Operational semantics: The meaning is specified by the computation steps executed on a machine. It is of intrest how it is obtained.
 - Denotational semantics: The meaning is modelled by mathematical objects that represent the effect of executing the program. It is of interest the effect, not how it is obtained.

The While Language: Abstract Syntax

n will range over numerals, Num *x* will range over variables, Var *a* will range over arithmetic expressions, Aexp *b* will range over boolean expressions, Bexp *c*, *S* will range over statements, Stm

$$a \hspace{.1in}
ightarrow \hspace{.1in} n \mid x \mid a_1 + a_2 \mid a_1 \star a_2 \mid a_1 - a_2$$

$$b \hspace{.1in}
ightarrow \hspace{.1in}$$
 true | false | $a_1 = a_2 \mid a_1 \leq a_2 \mid
eg b \mid b_1 \wedge b_2$

$$c \hspace{.1in}
ightarrow \hspace{.1in} x := a \mid { t skip} \mid c_1; c_2 \mid { t if} \hspace{.1in} b \hspace{.1in} c_1 \hspace{.1in} c_2 \mid { t while} \hspace{.1in} b \hspace{.1in} c_2$$

Example

The factorial program:

```
y:=1; while \neg(x=1) do (y:=y\starx; x:=x-1)
```

The abstract syntax tree:

Semantics of Arithmetic Expressions

- The meaning of an expression depends on the values bound to the variables that occur in the expression, e.g., x + 3.
- A state is a function from variables to values:

$$\mathsf{State} = \mathrm{Var} \to \mathbb{Z}$$

• The meaning of arithmetic expressions is a function:

$$\begin{array}{rcl} \mathcal{A} : \operatorname{Aexp} \to \operatorname{\mathsf{State}} \to \mathbb{Z} \\ & \mathcal{A}\llbracket a \rrbracket & : & \operatorname{\mathsf{State}} \to \mathbb{Z} \\ & \mathcal{A}\llbracket n \rrbracket (s) &= & n \\ & \mathcal{A}\llbracket x \rrbracket (s) &= & s(x) \\ \mathcal{A}\llbracket a_1 + a_2 \rrbracket (s) &= & \mathcal{A}\llbracket a_1 \rrbracket (s) + \mathcal{A}\llbracket a_2 \rrbracket (s) \\ & \mathcal{A}\llbracket a_1 \star a_2 \rrbracket (s) &= & \mathcal{A}\llbracket a_1 \rrbracket (s) \times \mathcal{A}\llbracket a_2 \rrbracket (s) \\ \mathcal{A}\llbracket a_1 - a_2 \rrbracket (s) &= & \mathcal{A}\llbracket a_1 \rrbracket (s) - \mathcal{A}\llbracket a_2 \rrbracket (s) \end{array}$$

Semantics of Boolean Expressions

• The meaning of boolean expressions is a function:

 $\mathcal{B}: \operatorname{Bexp} \to \mathsf{State} \to \mathsf{T}$

where $\mathbf{T} = \{true, false\}$.

 $\begin{array}{rcl} \mathcal{B}\llbracket b \rrbracket &: & \mathsf{State} \to \mathsf{T} \\ \mathcal{B}\llbracket \mathsf{true} \rrbracket(s) &= & true \\ \mathcal{B}\llbracket \mathsf{false} \rrbracket(s) &= & false \\ \mathcal{B}\llbracket a_1 = a_2 \rrbracket(s) &= & \mathcal{A}\llbracket a_1 \rrbracket(s) = \mathcal{A}\llbracket a_2 \rrbracket(s) \\ \mathcal{B}\llbracket a_1 \leq a_2 \rrbracket(s) &= & \mathcal{A}\llbracket a_1 \rrbracket(s) \leq \mathcal{A}\llbracket a_2 \rrbracket(s) \\ \mathcal{B}\llbracket \neg b \rrbracket(s) &= & \mathcal{B}\llbracket b \rrbracket(s) = false \\ \mathcal{B}\llbracket b_1 \wedge b_2 \rrbracket(s) &= & \mathcal{B}\llbracket b_1 \rrbracket(s) \wedge \mathcal{B}\llbracket b_2 \rrbracket(s) \end{array}$

Free Variables

The free variables of an arithmetic expression a are defined to be the set of variables occurring in it:

$$egin{array}{rll} FV(n) &=& \emptyset \ FV(x) &=& \{x\} \ FV(a_1+a_2) &=& FV(a_1)\cup FV(a_2) \ FV(a_1\star a_2) &=& FV(a_1)\cup FV(a_2) \ FV(a_1-a_2) &=& FV(a_1)\cup FV(a_2) \end{array}$$

Exercise) Define free variables of boolean expressions.

Property of Free Variables

Only the free variables influence the value of an expression.

Lemma

Let s and s' be two states satisfying that s(x) = s'(x) for all $x \in FV(a)$. Then, $\mathcal{A}\llbracket a \rrbracket(s) = \mathcal{A}\llbracket a \rrbracket(s')$.

Proof:

Property of Free Variables

Lemma

Let s and s' be two states satisfying that s(x) = s'(x) for all $x \in FV(b)$. Then, $\mathcal{B}\llbracket b \rrbracket(s) = \mathcal{B}\llbracket b \rrbracket(s')$.

Proof:

Substitution

 a[y → a₀]: the arithmetic expression that is obtained by replacing each occurrence of y in a by a₀.

$$egin{array}{rll} n[y\mapsto a_0]&=&n\ x[y\mapsto a_0]&=&igg\{ egin{array}{ll} a_0 & ext{if } x=y\ x & ext{if } x
eq y\ (a_1+a_2)[y\mapsto a_0]&=&(a_1[y\mapsto a_0])+(a_2[y\mapsto a_0])\ (a_1\star a_2)[y\mapsto a_0]&=&(a_1[y\mapsto a_0])\star(a_2[y\mapsto a_0])\ (a_1-a_2)[y\mapsto a_0]&=&(a_1[y\mapsto a_0])-(a_2[y\mapsto a_0]) \end{array}$$

• $s[y\mapsto v]$: the state s except that the value bound to y is v.

$$(s[y\mapsto v])(x)=\left\{egin{array}{cc} v & ext{if } x=y\ s(x) & ext{if } x
eq y \end{array}
ight.$$

Property of Substitution

The two concepts of substitutions are related:

Lemma

$$\mathcal{A}\llbracket a[y \mapsto a_0] \rrbracket(s) = \mathcal{A}\llbracket a \rrbracket(s[y \mapsto \mathcal{A}\llbracket a_0 \rrbracket(s)]) \text{ for all states } s.$$

Proof:

Operational Semantics

Operational semantics is concerned about how to execute programs and not merely what the execution results are.

- *Big-step operational semantics* describes how the overall results of executions are obtained.
- *Small-step operational semantics* describes how the individual steps of the computations take place.

In both kinds, the semantics is specified by a transition system $(\mathbb{S}, \rightarrow)$ where \mathbb{S} is the set of states (configurations) with two types:

- $\langle S,s \rangle$: a nonterminal state (i.e. the statement S is to be executed from the state s)
- s: a terminal state

The transition relation $(\rightarrow) \subseteq \mathbb{S} \times \mathbb{S}$ describes how the execution takes place. The difference between the two approaches are in the definitions of transition relation.

Big-step Operational Semantics

The transition relation specifies the relationship between the initial state and the final state:

$$\langle S,s
angle o s'$$

Transition relation is defined with inference rules of the form: A rule has the general form

$$\frac{\langle S_1, s_1 \rangle \to s_1', \dots, \langle S_n, s_n \rangle \to s_n'}{\langle S, s \rangle \to s'} \text{ if } \cdots$$

• S_1, \ldots, S_n are statements that constitute S_1 .

- A rule has a number of premises and one conclusion.
- A rule may also have a number of conditions that have to be fulfilled whenever the rule is applied.
- Rules without premises are called axioms.

Big-step Operational Semantics for While

$$\begin{split} \overline{\langle x := a, s \rangle} &\to s[x \mapsto \mathcal{A}\llbracket a \rrbracket(s)] \\ \overline{\langle \text{skip}, s \rangle} \to s \\ \frac{\langle S_1, s \rangle \to s'}{\langle S_1; S_2, s \rangle \to s''} \\ \frac{\langle S_1, s \rangle \to s'}{\langle \text{if } b \ S_1 \ S_2, s \rangle \to s'} \text{ if } \mathcal{B}\llbracket b \rrbracket(s) = \text{true} \\ \frac{\langle S_2, s \rangle \to s'}{\langle \text{if } b \ S_1 \ S_2, s \rangle \to s'} \text{ if } \mathcal{B}\llbracket b \rrbracket(s) = \text{false} \\ \frac{\langle S, s \rangle \to s'}{\langle \text{while } b \ S, s \rangle \to s''} \text{ if } \mathcal{B}\llbracket b \rrbracket(s) = \text{true} \\ \frac{\langle S, s \rangle \to s'}{\langle \text{while } b \ S, s \rangle \to s''} \text{ if } \mathcal{B}\llbracket b \rrbracket(s) = \text{false} \end{split}$$

Example

Example 2.1

Let us first consider the statement of Chapter 1:

$$(z:=x; x:=y); y:=z$$

Let s_0 be the state that maps all variables except x and y to 0 and has $s_0 = 5$ and $s_0 = 7$. Then an example of a derivation tree is

$$\begin{array}{c|c} \langle \mathbf{z}:=\mathbf{x}, \, s_0 \rangle \to s_1 & \langle \mathbf{x}:=\mathbf{y}, \, s_1 \rangle \to s_2 \\ \hline & \langle \mathbf{z}:=\mathbf{x}; \, \mathbf{x}:=\mathbf{y}, \, s_0 \rangle \to s_2 & \langle \mathbf{y}:=\mathbf{z}, \, s_2 \rangle \to s_3 \\ \hline & \langle (\mathbf{z}:=\mathbf{x}; \, \mathbf{x}:=\mathbf{y}); \, \mathbf{y}:=\mathbf{z}, \, s_0 \rangle \to s_3 \end{array}$$

where we have used the abbreviations:

$$\begin{array}{rcl} s_1 & = & s_0[\mathbf{z} \mapsto \mathbf{5}] \\ \\ s_2 & = & s_1[\mathbf{x} \mapsto \mathbf{7}] \\ \\ s_3 & = & s_2[\mathbf{y} \mapsto \mathbf{5}] \end{array}$$

Exercise

Let s be a state with s(x) = 3. Find s' such that

(y:=1; while \neg (x=1) do (y:=y \star x; x:=x-1), s) \rightarrow s'

Execution Types

We say the execution of a statement old S on a state old s

- ullet terminates if and only if there is a state s' such that $\langle S,s
 angle
 ightarrow s'$ and
- loops if and only if there is no state s' such that $\langle S,s\rangle \to s'.$

We say a statement S always terminates if its execution on a state s terminates for all states s, and always loops if its execution on a state s loops for all states s.

Examples:

- while true do skip
- while ¬(x=1) do (y:=y★x; x:=x-1)

Semantic Equivalence

We say S_1 and S_2 are semantically equivalent, denoted $S_1 \equiv S_2$, if the following is true for all states s and s':

$$\langle S_1,s
angle
ightarrow s'$$
 if and only if $\langle S_2,s
angle
ightarrow s'$

Example:

while b do $S \equiv$ if b then (S; while b do S) else skip

Semantic Function for Statements

The semantic function for statements is the partial function:

$$\mathcal{S}_b:\operatorname{Stm} o(\operatorname{\mathsf{State}}\hookrightarrow\operatorname{\mathsf{State}})$$
 $\mathcal{S}_b\llbracket S
rbracket(s)=\left\{egin{array}{cc} s'& ext{if }\langle S,s
angle o s'\\ ext{undef}& ext{otherwise}\end{array}
ight.$

Examples:

- $\mathcal{S}_b[[y:=1; \text{ while } \neg(x=1) \text{ do } (y:=y \star x; x:=x-1)]](s[x \mapsto 3])$
- $\mathcal{S}_b[[while true do skip]](s)$

Summary of While

The syntax is defined by the grammar:

$$egin{array}{rcl} a & o & n \mid x \mid a_1 + a_2 \mid a_1 \star a_2 \mid a_1 - a_2 \ b & o & ext{true} \mid ext{false} \mid a_1 = a_2 \mid a_1 \leq a_2 \mid
eg b \mid b_1 \wedge b_2 \ c & o & x := a \mid ext{skip} \mid c_1; c_2 \mid ext{if} \; b \; c_1 \; c_2 \mid ext{while} \; b \; c \end{array}$$

The semantics is defined by the functions:

$\mathcal{A}\llbracket a rbracket$:	$State \to \mathbb{Z}$
$\mathcal{B}[\![b]\!]$:	$State \to T$
$\mathcal{S}_b\llbracket c rbracket$:	$State \hookrightarrow State$

Implementing Big-Step Interpreter in OCaml

```
type var = string
type aexp =
  | Int of int
  | Var of var
  | Plus of aexp * aexp
  | Mult of aexp * aexp
  | Minus of aexp * aexp
type bexp =
   True
  | False
  | Eq of aexp * aexp
  | Le of aexp * aexp
  | Neg of bexp
  | Conj of bexp * bexp
type cmd =
  | Assign of var * aexp
    Skip
  | Seq of cmd * cmd
  | If of bexp * cmd * cmd
   While of bexp * cmd
```

Syntax:

Implementing Big-Step Interpreter

```
let fact =
  Seq (Assign ("y", Int 1),
    While (Neg (Eq (Var "x", Int 1)),
      Seq (Assign("y", Mult(Var "y", Var "x")),
           Assign("x", Minus(Var "x", Int 1)))
       )
  )
module State = struct
  type t = (var * int) list
  let empty = []
  let rec lookup s x =
    match s with
    | [] -> raise (Failure (x ^ "is not bound in state"))
    |(y,v)::s' \rightarrow if x = y then v else lookup s' x
  let update s x v = (x,v)::s
end
let init_s = update empty "x" 3
```

Implementing Big-Step Interpreter

```
let rec eval_a : aexp -> State.t -> int
=fun a s ->
  match a with
  | Int n \rightarrow n
  | Var x -> State.lookup s x
  | Plus (a1, a2) \rightarrow (eval_a a1 s) + (eval_a a2 s)
  | Mult (a1, a2) \rightarrow (eval_a a1 s) \ast (eval_a a2 s)
  | Minus (a1, a2) \rightarrow (eval a a1 s) - (eval a a2 s)
let rec eval_b : bexp -> State.t -> bool
=fun b s \rightarrow
  match b with
  | True \rightarrow true
  | False -> false
  | Eq (a1, a2) -> (eval_a a1 s) = (eval_a a2 s)
  | Le (a1, a2) \rightarrow (eval a a1 s) <= (eval a a2 s)
  | Neg b' -> not (eval_b b' s)
  | Conj (b1, b2) \rightarrow (eval b b1 s) && (eval b b2 s)
```

Implementing Big-Step Interpreter

```
let rec eval_c : cmd -> State.t -> State.t
=fun c s ->
match c with
| Assign (x, a) -> State.update s x (eval_a a s)
| Skip -> s
| Seq (c1, c2) -> eval_c c2 (eval_c c1 s)
| If (b, c1, c2) -> eval_c (if eval_b b s then c1 else c2) s
| While (b, c) ->
if eval_b b s then eval_c (While (b,c)) (eval_c c s)
else s
```

```
let _ =
```

```
print_int (State.lookup (eval_c fact init_s) "y");
print_newline ()
```

Small-step Operational Semantics

The individual computation steps are described by the transition relation of the form:

$$\langle S,s
angle \Rightarrow \gamma$$

where γ either is non-terminal state $\langle S', s' \rangle$ or terminal state s'. The transition expresses the first step of the execution of S from state s.

- If $\gamma = \langle S', s' \rangle$, then the execution of S from s is not completed and the remaining computation continues with $\langle S', s' \rangle$.
- If $\gamma = s'$, then the execution of S from s has terminated and the final state is s'.

We say $\langle S, s \rangle$ is stuck if there is no γ such that $\langle S, s \rangle \Rightarrow \gamma$ (no stuck state for **While**).

Small-step Operational Semantics for While

$$\overline{\langle x := a, s \rangle} \Rightarrow s[x \mapsto \mathcal{A}\llbracket a \rrbracket(s)]$$

$$\overline{\langle skip, s \rangle} \Rightarrow s$$

$$\frac{\langle S_1, s \rangle \Rightarrow \langle S'_1, s' \rangle}{\langle S_1; S_2, s \rangle \Rightarrow \langle S'_1; S_2, s' \rangle}$$

$$\frac{\langle S_1, s \rangle \Rightarrow s'}{\langle S_1; S_2, s \rangle \Rightarrow \langle S_2, s' \rangle}$$

$$\overline{\langle if \ b \ S_1 \ S_2, s \rangle \Rightarrow \langle S_1, s \rangle} \text{ if } \mathcal{B}\llbracket b \rrbracket(s) = \text{true}$$

$$\overline{\langle if \ b \ S_1 \ S_2, s \rangle \Rightarrow \langle S_2, s \rangle} \text{ if } \mathcal{B}\llbracket b \rrbracket(s) = \text{false}$$

 $\overline{\langle \texttt{while}\;b\;S,s\rangle \Rightarrow \langle \texttt{if}\;b\;(S;\;\texttt{while}\;b\;S)\;\texttt{skip},s\rangle}$

Derivation Sequence

A derivation sequence of a statement S starting in state s is either

• A finite sequence

$$\gamma_0, \gamma_1, \gamma_2, \cdots, \gamma_k$$

which is sometimes written

$$\gamma_0 \Rightarrow \gamma_1 \Rightarrow \gamma_2 \Rightarrow \dots \Rightarrow \gamma_k$$

such that

$$\gamma_0 = \langle S, s
angle, \quad \gamma_i \Rightarrow \gamma_{i+1} ext{ for } 0 \leq i \leq k$$

and γ_k is either a terminal configuration or a stuck configuration. • An infinite sequence

$$\gamma_0,\gamma_1,\gamma_2,\cdots$$

which is sometimes written

$$\gamma_0 \Rightarrow \gamma_1 \Rightarrow \gamma_2 \Rightarrow \cdots$$

consisting of configurations satisfying $\gamma_0 = \langle S,s \rangle$ and $\gamma_i \Rightarrow \gamma_{i+1}$ for $0 \leq i$.

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Example 2.14

Consider the statement

$$(z := x; x := y); y := z$$

of Chapter 1, and let s_0 be the state that maps all variables except x and y to 0 and that has $s_0 x = 5$ and $s_0 y = 7$. We then have the derivation sequence

$$\begin{split} &\langle (\mathbf{z} := \mathbf{x}; \ \mathbf{x} := \mathbf{y}); \ \mathbf{y} := \mathbf{z}, \ s_0 \rangle \\ &\Rightarrow \langle \mathbf{x} := \mathbf{y}; \ \mathbf{y} := \mathbf{z}, \ s_0 [\mathbf{z} {\mapsto} \mathbf{5}] \rangle \\ &\Rightarrow \langle \mathbf{y} := \mathbf{z}, \ (s_0 [\mathbf{z} {\mapsto} \mathbf{5}]) [\mathbf{x} {\mapsto} \mathbf{7}] \rangle \\ &\Rightarrow ((s_0 [\mathbf{z} {\mapsto} \mathbf{5}]) [\mathbf{x} {\mapsto} \mathbf{7}]) [\mathbf{y} {\mapsto} \mathbf{5}] \end{split}$$

Corresponding to *each* of these steps, we have *derivation trees* explaining why they take place. For the first step

$$\langle (\mathtt{z}:=\mathtt{x};\,\mathtt{x}:=\mathtt{y});\,\mathtt{y}:=\mathtt{z},\,s_0\rangle \Rightarrow \langle \mathtt{x}:=\mathtt{y};\,\mathtt{y}:=\mathtt{z},\,s_0[\mathtt{z}{\mapsto} \mathtt{5}]\rangle$$

the derivation tree is

$$\begin{array}{c} \langle \mathbf{z} := \mathbf{x}, \, s_0 \rangle \Rightarrow s_0 [\mathbf{z} \mapsto \mathbf{5}] \\\\ \hline \\ \langle \mathbf{z} := \mathbf{x}; \, \mathbf{x} := \mathbf{y}, \, s_0 \rangle \Rightarrow \langle \mathbf{x} := \mathbf{y}, \, s_0 [\mathbf{z} \mapsto \mathbf{5}] \rangle \\\\ \hline \\ \hline \\ \langle \mathbf{z} := \mathbf{x}; \, \mathbf{x} := \mathbf{y}); \, \mathbf{y} := \mathbf{z}, \, s_0 \rangle \Rightarrow \langle \mathbf{x} := \mathbf{y}; \, \mathbf{y} := \mathbf{z}, \, s_0 [\mathbf{z} \mapsto \mathbf{5}] \rangle \end{array}$$

and it has been constructed from the axiom $[ass_{sos}]$ and the rules $[comp_{sos}^1]$ and $[comp_{sos}^2]$. The derivation tree for the second step is constructed in a similar way using only $[ass_{sos}]$ and $[comp_{sos}^2]$, and for the third step it simply is an instance of $[ass_{sos}]$.

Example: Factorial

Assume that s(x) = 3.

$$\begin{array}{l} \langle \mathbf{y}:=1; \ \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s \rangle \\ \Rightarrow \langle \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 1] \rangle \\ \Rightarrow \langle \text{if } \neg(\mathbf{x}=1) \ \text{then} \ ((\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1); \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1)) \\ \text{else } skip, s[\mathbf{y} \mapsto 1] \rangle \\ \Rightarrow \langle (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1); \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 1] \rangle \\ \Rightarrow \langle \mathbf{x}:=\mathbf{x}-1; \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 3] \rangle \\ \Rightarrow \langle \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 3] [\mathbf{x} \mapsto 2] \rangle \\ \Rightarrow \langle \text{if } \neg(\mathbf{x}=1) \ \text{then} \ ((\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1); \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1)) \\ \text{else } skip, s[\mathbf{y} \mapsto 3] [\mathbf{x} \mapsto 2] \rangle \\ \Rightarrow \langle (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1); \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 3] [\mathbf{x} \mapsto 2] \rangle \\ \Rightarrow \langle \mathbf{x}:=\mathbf{x}-1; \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 6] [\mathbf{x} \mapsto 2] \rangle \\ \Rightarrow \langle \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 6] [\mathbf{x} \mapsto 2] \rangle \\ \Rightarrow \langle \text{while } \neg(\mathbf{x}=1) \ \text{do} \ (\mathbf{y}:=\mathbf{y}\star\mathbf{x}; \ \mathbf{x}:=\mathbf{x}-1), s[\mathbf{y} \mapsto 6] [\mathbf{x} \mapsto 1] \rangle \\ \Rightarrow s[\mathbf{y} \mapsto 6] [\mathbf{x} \mapsto 1] \end{aligned}$$

Other Notations

- We write $\gamma_0 \Rightarrow^i \gamma_i$ to indicate that there are i steps in the execution from γ_0 to γ_i .
- We write $\gamma_0 \Rightarrow^* \gamma_i$ to indicate that there are a finite number of steps.
- We say that the execution of a statement S on a state s terminates if and only if there is a finite derivation sequence starting with (S, s).
- The execution loops if and only if there is an infinite derivation sequence starting with (S, s).

Semantic Function

The semantic function \mathcal{S}_s for small-step semantics:

$$\mathcal{S}_s:\operatorname{Stm} o(\operatorname{\mathsf{State}}\hookrightarrow\operatorname{\mathsf{State}})$$
 $\mathcal{S}_s\llbracket S
rbracket(s)=\left\{egin{array}{cc} s'& ext{if }\langle S,s
angle\Rightarrow^*s'\\ ext{undef} \end{array}
ight.$

Implementing Small-Step Interpreter

```
type conf =
  | NonTerminated of cmd * State.t
  | Terminated of State.t
let rec next : conf \rightarrow conf
=fun conf ->
  match conf with
  | Terminated _ -> raise (Failure "Must not happen")
  | NonTerminated (c. s) ->
    match c with
    | Assign (x, a) -> Terminated (State.update s x (eval_a a s))
    | Skip -> Terminated s
    | Seq (c1, c2) -> (
       match (next (NonTerminated (c1,s))) with
       | NonTerminated (c', s') -> NonTerminated (Seq (c', c2), s')
       | Terminated s' -> NonTerminated (c2, s')
      )
    | If (b, c1, c2) ->
      if eval b b s then NonTerminated (c1. s) else NonTerminated (c2. s)
    | While (b, c) -> NonTerminated (If (b, Seq (c, While (b,c)), Skip), s)
```

Implementing Small-Step Interpreter

```
let rec next_trans : conf -> State.t
=fun conf ->
match conf with
  | Terminated s -> s
  | _ -> next_trans (next conf)
```

```
let _ =
```

```
print_int (State.lookup (next_trans (NonTerminated (fact,init_s))) "y");
print_newline ()
```

Summary of While

We have defined the operational semantics of While.

- *Big-step operational semantics* describes how the overall results of executions are obtained.
- *Small-step operational semantics* describes how the individual steps of the computations take place.

The big-step and small-step operational semantics are equivalent:

Theorem

For every statement S of While, we have $S_b[\![S]\!] = S_s[\![S]\!]$.

Next

We will extend While with blocks and procedures: e.g.,

begin proc fac is begin var z:=x; if x=1 then skip else $(x:=x-1;\, \texttt{call fac};\, y:=z{\star}y)$ end; $(y:=1;\,\texttt{call fac})$

end

Materials

• This lecture is based on Chapters 1–3 of the book:



Read those chapters if you are unfamiliar with language semantics.

• If you are uncomfortable with OCaml, take my undergraduate course on programming languages or watch the following video (in Korean):

https://www.youtube.com/watch?v=EDG9diprxQ0