

COSE212: Programming Languages

Lecture 12 — Automatic Type Inference (2)

Hakjoo Oh
2017 Fall

Finding a Solution of Type Equations

Find the values of type variables that make all the equations true.

$$\underbrace{\underbrace{\underbrace{\underbrace{\text{proc } (f)}_{t_f} \text{ proc } (x)}_{t_x} ((f \ 3) - (f \ x))}_{t_2}}_{t_1}}_{t_0}$$

Equations	Solution
$t_0 = t_f \rightarrow t_1$	$t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (\text{int} \rightarrow \text{int})$
$t_1 = t_x \rightarrow t_2$	$t_1 = \text{int} \rightarrow \text{int}$
$t_3 = \text{int}$	$t_2 = \text{int}$
$t_4 = \text{int}$	$t_3 = \text{int}$
$t_2 = \text{int}$	$t_4 = \text{int}$
$t_f = \text{int} \rightarrow t_3$	$t_f = \text{int} \rightarrow \text{int}$
$t_x = t_x \rightarrow t_4$	$t_x = \text{int}$

Static type systems find such a solution using *unification algorithm*.

Example 1

The calculation is split into equations to be solved and substitution found so far. Initially, the substitution is empty:

	Equations	Substitution
t_0	$= t_f \rightarrow t_1$	
t_1	$= t_x \rightarrow t_2$	
t_3	$= \text{int}$	
t_4	$= \text{int}$	
t_2	$= \text{int}$	
t_f	$= \text{int} \rightarrow t_3$	
t_f	$= t_x \rightarrow t_4$	

Example 1

Consider each equation in turn. If the equation's left-hand side is a variable, move it to the substitution:

Equations	Substitution
$t_1 = t_x \rightarrow t_2$	$t_0 = t_f \rightarrow t_1$
$t_3 = \text{int}$	
$t_4 = \text{int}$	
$t_2 = \text{int}$	
$t_f = \text{int} \rightarrow t_3$	
$t_f = t_x \rightarrow t_4$	

Example 1

Move the next equation to the substitution and propagate the information to the existing substitution (i.e., substitute the right-hand side for each occurrence of t_1):

Equations	Substitution
$t_3 = \text{int}$	$t_0 = t_f \rightarrow (t_x \rightarrow t_2)$
$t_4 = \text{int}$	$t_1 = t_x \rightarrow t_2$
$t_2 = \text{int}$	
$t_f = \text{int} \rightarrow t_3$	
$t_f = t_x \rightarrow t_4$	

Example 1

Same for the next three equations:

Equations	Substitution
$t_4 = \text{int}$	$t_0 = t_f \rightarrow (t_x \rightarrow t_2)$
$t_2 = \text{int}$	$t_1 = t_x \rightarrow t_2$
$t_f = \text{int} \rightarrow t_3$	$t_3 = \text{int}$
$t_f = t_x \rightarrow t_4$	

Equations	Substitution
$t_2 = \text{int}$	$t_0 = t_f \rightarrow (t_x \rightarrow t_2)$
$t_f = \text{int} \rightarrow t_3$	$t_1 = t_x \rightarrow t_2$
$t_f = t_x \rightarrow t_4$	$t_3 = \text{int}$
	$t_4 = \text{int}$

Equations	Substitution
$t_f = \text{int} \rightarrow t_3$	$t_0 = t_f \rightarrow (t_x \rightarrow \text{int})$
$t_f = t_x \rightarrow t_4$	$t_1 = t_x \rightarrow \text{int}$
	$t_3 = \text{int}$
	$t_4 = \text{int}$
	$t_2 = \text{int}$

Example 1

Consider the next equation $t_f = \text{int} \rightarrow t_3$. The equation contains t_3 , which is already bound to int in the substitution. Substitute int for t_3 in the equation. This is called *applying* the substitution to the equation.

Equations	Substitution
$t_f = \text{int} \rightarrow \text{int}$	$t_0 = t_f \rightarrow (t_x \rightarrow \text{int})$
$t_f = t_x \rightarrow t_4$	$t_1 = t_x \rightarrow \text{int}$
	$t_3 = \text{int}$
	$t_4 = \text{int}$
	$t_2 = \text{int}$

Move the resulting equation to the substitution and update it.

Equations	Substitution
$t_f = t_x \rightarrow t_4$	$t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (t_x \rightarrow \text{int})$
	$t_1 = t_x \rightarrow \text{int}$
	$t_3 = \text{int}$
	$t_4 = \text{int}$
	$t_2 = \text{int}$
	$t_f = \text{int} \rightarrow \text{int}$

Example 1

Apply the substitution to the equation:

Equations	Substitution
$\text{int} \rightarrow \text{int} = t_x \rightarrow \text{int}$	$t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (t_x \rightarrow \text{int})$
	$t_1 = t_x \rightarrow \text{int}$
	$t_3 = \text{int}$
	$t_4 = \text{int}$
	$t_2 = \text{int}$
	$t_f = \text{int} \rightarrow \text{int}$

If neither side of the equation is a variable, simplify the equation by yielding two new equations:

Equations	Substitution
$\text{int} = t_x$	$t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (t_x \rightarrow \text{int})$
$\text{int} = \text{int}$	$t_1 = t_x \rightarrow \text{int}$
	$t_3 = \text{int}$
	$t_4 = \text{int}$
	$t_2 = \text{int}$
	$t_f = \text{int} \rightarrow \text{int}$

Example 1

Switch the sides of the first equation and move it to the substitution:

Equations	Substitution
$\text{int} = \text{int}$	$t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (\text{int} \rightarrow \text{int})$
	$t_1 = \text{int} \rightarrow \text{int}$
	$t_3 = \text{int}$
	$t_4 = \text{int}$
	$t_2 = \text{int}$
	$t_f = \text{int} \rightarrow \text{int}$
	$t_x = \text{int}$

The final substitution is the solution of the original equations.

Example 2

$$\text{proc } \underbrace{(f)}_{t_f} \underbrace{(f \ 11)}_{t_1}$$
$$\underbrace{\hspace{10em}}_{t_0}$$
$$t_0 = t_f \rightarrow t_1$$
$$t_f = \text{int} \rightarrow t_1$$

Example 2

1

Equations	Substitution
$t_0 = t_f \rightarrow t_1$	
$t_f = \text{int} \rightarrow t_1$	

2

Equations	Substitution
$t_f = \text{int} \rightarrow t_1$	$t_0 = t_f \rightarrow t_1$

3

Equations	Substitution
	$t_0 = (\text{int} \rightarrow t_1) \rightarrow t_1$
	$t_f = \text{int} \rightarrow t_1$

The type is *polymorphic* in t_1 .

Example 3

if \underbrace{x}_{t_x} then $\underbrace{(x - 1)}_{t_1}$ else 0

$\underbrace{\hspace{10em}}_{t_0}$

$t_x = \text{bool}$

$t_1 = t_0$

int = t_0

$t_x = \text{int}$

$t_1 = \text{int}$

Example 3

The equations have no solutions because, during the unification algorithm, we encounter the following contradictory state:

Equations	Substitution
$\text{bool} = \text{int}$	$t_x = \text{bool}$
$t_1 = \text{int}$	$t_1 = \text{int}$
	$t_0 = \text{int}$

Because `bool` and `int` cannot be equal, there is no solution to the equations.

Example 4

$$\text{proc } \underbrace{(f)}_{t_f} \underbrace{(\text{iszero } \underbrace{(f f)}_{t_2})}_{t_1}$$
$$\underbrace{\hspace{15em}}_{t_0}$$
$$t_0 = t_f \rightarrow t_1$$
$$t_1 = \text{bool}$$
$$t_2 = \text{int}$$
$$t_f = t_f \rightarrow t_2$$

Example 4

Solving as usual, we encounter a problem:

Equations	Substitution
$t_f = t_f \rightarrow \text{int}$	$t_0 = t_f \rightarrow \text{bool}$
	$t_1 = \text{bool}$
	$t_2 = \text{int}$

- There is no type t_f that satisfies the equation, because the right-hand side of the equation is always larger than the left.
- If we ever deduce an equation of the form $t = \dots t \dots$ where the type variable t occurs in the right-hand side, we must conclude that there is no solution. This is called *occurrence check*.

Unification Algorithm

For each equation in turn,

- Apply the current substitution to the equation.
- If the equation is always true (e.g. $\text{int} = \text{int}$), discard it.
- If the left- and right-hand sides are base types and contradictory (e.g. $\text{bool} = \text{int}$), the algorithm fails.
- If neither side is a variable (e.g. $\text{int} \rightarrow t_1 = t_2 \rightarrow \text{bool}$), simplify the equation, which eventually generates an equation whose left- or right-hand side is a variable.
- If the left-hand side is not a variable, switch the sides.
- If the left-hand side variable occurs in the right-hand side, the algorithm fails.
- Otherwise, move it to the substitution and substitute the right-hand side for each occurrence of the variable in the substitution.

Exercise 1

`let $x = 4$ in (x 3)`

Exercise 2

let $f = \text{proc } (z) z \text{ in proc } (x) ((f x) - 1)$

Exercise 3

let $p = \text{iszero } 1$ in if p then 88 else 99

Exercise 4

```
let f = proc (x) x in if (f (iszero0)) then (f 11) else (f 22)
```

Summary

Automatic type inference:

- derive type equations from the program text, and
- solve the equations by unification algorithm.